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## Freeness of Multi-Reflection Arrangements via Primitive Vector Fields

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# FREENESS OF MULTI-REFLECTION ARRANGEMENTS VIA PRIMITIVE VECTOR FIELDS 

TORSTEN HOGE, TOSHIYUKI MANO, GERHARD RÖHRLE, AND CHRISTIAN STUMP


#### Abstract

In 2002, Terao showed that every reflection multi-arrangement of a real reflection group with constant multiplicity is free by providing a basis of the module of derivations. We first generalize Terao's result to multi-arrangements stemming from well-generated unitary reflection groups, where the multiplicity of a hyperplane depends on the order of its stabilizer. Here the exponents depend on the exponents of the dual reflection representation. We then extend our results further to all imprimitive irreducible unitary reflection groups. In this case the exponents turn out to depend on the exponents of a certain Galois twist of the dual reflection representation that comes from a Beynon-Lusztig type semi-palindromicity of the fake degrees.


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## 1. Introduction

In his seminal work [Zie89], Ziegler introduced the concept of multi-arrangements generalizing the notion of hyperplane arrangements. In [Ter02], Terao showed that every reflection multi-arrangement of a real reflection group with constant multiplicities is free, see also the approach by Yoshinaga [Yos02]. Our aim is to generalize this result from real reflection groups to unitary reflection groups, see Theorems 1.1 and 1.2.

More precisely, we first extend Yoshinaga's construction of a basis of the module of derivations to well-generated unitary reflection groups by using recent developments of flat systems of invariants in the context of isomonodromic deformations and differential equations of Okubo type due to Kato, Mano and Sekiguchi [KMS16]. We then further extend the results to the imprimitive reflection groups by use of a permutation of the irreducible complex representations that is studied in the context of the representation theory of the Hecke algebra and which induces a semi-palindromic property on the fake degree polynomial [Mal99, Opd00, GG12].

Suppose that $W$ is an irreducible unitary reflection group with reflection representation $V \cong \mathbb{C}^{\ell}$. Denote the set of reflections by $\mathcal{R}=\mathcal{R}(W)$, and the associated reflection

[^0]arrangement in $V$ by $\mathscr{A}=\mathscr{A}(W)$. For $H \in \mathscr{A}$, let $e_{H} \in \mathbb{N}:=\{0,1,2, \ldots\}$ denote the order of the pointwise stabilizer of $H$ in $W$, and consider the multiplicity function
$$
\omega: \mathscr{A} \rightarrow \mathbb{N}, \quad \omega(H)=e_{H}
$$
for each hyperplane $H \in \mathscr{A}$. For $m \in \mathbb{N}$ let $m \omega$ and $m \omega+1$ denote the multiplicities defined by $m \omega(H)=m e_{H}$ and $m \omega(H)+1=m e_{H}+1$ for $H \in \mathscr{A}$, respectively. Following [GG12], the Coxeter number of $W$ is given by
$$
h=h_{W}:=\frac{1}{\ell} \sum_{H \in \mathscr{A}} e_{H}=\frac{1}{\ell}(|\mathcal{R}|+|\mathscr{A}|),
$$
generalizing the usual Coxeter number of a real reflection group to irreducible unitary reflection groups. Let $\operatorname{Irr}(W)$ denote the irreducible complex representations of $W$ up to isomorphism. For $U$ in $\operatorname{Irr}(W)$ of dimension $d$, denote by
$$
\exp _{U}(W):=\left\{n_{1}(U) \leq \ldots \leq n_{d}(U)\right\}
$$
the $U$-exponents of $W$ given by the $d$ homogeneous degrees in the coinvariant algebra of $W$ in which $U$ appears. In particular, the exponents of $W$ are
$$
\exp (W):=\exp _{V}(W)=\left\{n_{1}(V) \leq \ldots \leq n_{\ell}(V)\right\}
$$
and the coexponents of $W$ are
$$
\operatorname{coexp}(W):=\exp _{V^{*}}(W)=\left\{n_{1}\left(V^{*}\right) \leq \ldots \leq n_{\ell}\left(V^{*}\right)\right\}
$$

The group $W$ is well-generated if $n_{i}(V)+n_{\ell+1-i}\left(V^{*}\right)=h$, e.g., see [OS80, Mal99, Bes15].
We are now in a position to state our first main result, generalizing Terao's theorem from [Ter02] to the well-generated case.

Theorem 1.1. Let $W$ be an irreducible, well-generated unitary reflection group with reflection arrangement $\mathscr{A}(W)$. Let $\omega: \mathscr{A}(W) \rightarrow \mathbb{N}$ given by $\omega(H)=e_{H}$, and let $m \in \mathbb{N}$. Then
(i) the reflection multi-arrangement $(\mathscr{A}(W), m \omega)$ is free with exponents

$$
\exp (\mathscr{A}(W), m \omega)=\{m h, \ldots, m h\}
$$

(ii) the reflection multi-arrangement $(\mathscr{A}(W), m \omega+1)$ is free with exponents

$$
\exp (\mathscr{A}(W), m \omega+1)=\left\{m h+n_{1}\left(V^{*}\right), \ldots, m h+n_{\ell}\left(V^{*}\right)\right\} .
$$

Note from above that $\operatorname{coexp}(W)=\exp _{V^{*}}(W)=\left\{n_{1}\left(V^{*}\right), \ldots, n_{\ell}\left(V^{*}\right)\right\}$.
In the special case when $W$ is a Coxeter group, Theorem 1.1 recovers Terao's theorem [Ter02], as then $\omega \equiv 2$ and $\operatorname{coexp}(W)=\exp (W)$.

We prove this theorem in Section 3. Indeed, we extend Yoshinaga's construction [Yos02, Thm. 1] of a basis of the module of derivations to well-generated groups by using a recent construction due to Kato, Mano and Sekiguchi [KMS16]. See Theorem 3.18 for the precise formulation, which is our generalization of [Yos02, Thm. 7] to the well-generated setting.

In [KMS16], the authors construct flat systems of invariants of well-generated unitary reflection groups in the context of isomonodromic deformations and differential equations of Okubo type. For real reflection groups, the notion of flat systems of invariants was introduced by Saito, Yano and Sekiguchi in [SYS80]. The existence of such flat systems was shown in loc. cit. in all real types except $E_{7}$ and $E_{8}$. Saito then gave a uniform construction in all real types in [Sai93].

Our second main result extends Theorem 1.1 further to the infinite three-parameter family $W=G(r, p, \ell)$ of imprimitive reflection groups. It turns out that the corresponding multi-arrangements are also free. However, the description of the exponents is considerably more involved and depends on the representation theory of the Hecke algebra associated to the group $W$. To this end, let $\Psi$ denote the permutation on $\operatorname{Irr}(W)$ introduced by Malle in [Mal99, Sec. 6C], having the semi-palindromic property on the fake degrees of $W$. This is, for any $U$ in $\operatorname{Irr}(W)$ of dimension $d$, we have

$$
n_{i}(U)+n_{d+1-i}\left(\Psi\left(U^{*}\right)\right)=h_{U},
$$

where $h_{U}=|\mathscr{A}|-\sum_{r \in \mathcal{R}} \chi(r) / \chi(1)$ with $\chi$ being the character of $U$. A direct calculation shows that $h_{V}=h_{W}$ is the Coxeter number of $W$. Moreover, the permutation $\Psi$ of $\operatorname{Irr}(W)$ is the identity if and only if $W$ is well-generated [Mal99, Cor. 4.9].

Theorem 1.2. Let $W=G(r, p, \ell)$ with reflection arrangement $\mathscr{A}(W)$. Let $\omega: \mathscr{A}(W) \rightarrow$ $\mathbb{N}$ given by $\omega(H)=e_{H}$, and let $m \in \mathbb{N}$. Then
(i) the reflection multi-arrangement $(\mathscr{A}(W), m \omega)$ is free with exponents

$$
\exp (\mathscr{A}(W), m \omega)=\{m h, \ldots, m h\}
$$

(ii) the reflection multi-arrangement $(\mathscr{A}(W), m \omega+1)$ is free with exponents

$$
\exp (\mathscr{A}(W), m \omega+1)=\left\{m h+n_{1}\left(\Psi^{-m}\left(V^{*}\right)\right), \ldots, m h+n_{\ell}\left(\Psi^{-m}\left(V^{*}\right)\right)\right\} .
$$

Note this time that $\exp _{\Psi^{-m}\left(V^{*}\right)}(W)=\left\{n_{1}\left(\Psi^{-m}\left(V^{*}\right)\right), \ldots, n_{\ell}\left(\Psi^{-m}\left(V^{*}\right)\right)\right\}$. We prove a more general result in Theorem 4.1.

Remarks 1.3. (i) The group $G(r, p, \ell)$ is well-generated if and only if $p \in\{1, r\}$. Thus, Theorem 1.2 extends Theorem 1.1 to the class of imprimitive reflection groups that are not well-generated.
(ii) While the simple arrangements of the reflection groups $G(r, 1, \ell)$ and $G(r, p, \ell)$ for $1<p<r$ coincide, the multi-arrangements above depend on the underlying group, since the multiplicities of the coordinate hyperplanes differ.
(iii) Theorems 1.1 and 1.2 only leave unresolved the remaining eight irreducible unitary reflection groups of exceptional type that are not well-generated, namely

$$
\mathcal{G}_{\mathrm{exc}}=\left\{G_{7}, G_{11}, G_{12}, G_{13}, G_{15}, G_{19}, G_{22}, G_{31}\right\} .
$$

Computational evidence for each of these remaining groups with small values for the parameter $m \in \mathbb{N}$ suggests that Theorem 1.2 also holds with $W=G(r, p, \ell)$ replaced by $W \in \mathcal{G}_{\text {exc }}$.
(iv) The semi-palindromic property of the permutation $\Psi$ of $\operatorname{Irr}(W)$ in Theorem 1.2 is an analogue of a semi-palindromicity of the fake degrees as observed by Beynon and Lusztig [BL78, Prop. A] and later explained by Opdam [Opd95]. The definition of $\Psi$ depends on the representation theory of the corresponding Hecke algebra [Ma199, Opd00]. Moreover, it plays a crucial role in the study of rational Cherednik algebras [GG12, Thm. 1.6]. The intrinsic appearance of $\Psi$ in the present context of multi-derivations of reflection groups is rather unexpected.

The paper is organized as follows. In Section 2, we provide all needed background on hyperplane arrangements and unitary reflection groups. The proof of Theorem 1.1 is carried out in Section 3, along with its strengthened form, Theorem 3.18. Theorem 1.2 is proved in the final Section 4 as a consequence of Theorem 4.1.

## 2. Preliminaries

We first provide some basic material on hyperplane arrangements and multi-arrangements, and their modules of derivations. We then recall the needed background on unitary reflection groups. For general information about reflection groups and their arrangements, we refer the reader to [Bou68, OS82, Zie89, OT92].
2.1. Multi-arrangements and their modules of derivations. Let $S=S\left(V^{*}\right)$ denote the ring of polynomial functions on $V$ considered as the symmetric algebra of the dual space $V^{*}$. If $x_{1}, \ldots, x_{\ell}$ is a basis of $V^{*}$, we identify $S$ with the polynomial ring $\mathbb{C}\left[x_{1}, \ldots, x_{\ell}\right]$. Letting $S_{p}$ denote the $\mathbb{C}$-subspace of $S$ consisting of the homogeneous polynomials of degree $p$ (along with 0 ), $S$ is naturally $\mathbb{Z}$-graded by $S=\oplus_{p \in \mathbb{Z}} S_{p}$, where we consider $S_{p}=0$ for $p<0$.

Let $\operatorname{Der}_{S}$ be the $S$-module of $\mathbb{C}$-derivations of $S$. Then $\partial_{x_{1}}, \ldots, \partial_{x_{\ell}}$ is an $S$-basis of $\operatorname{Der}_{S}$. We say that $\theta \in \operatorname{Der}_{S}$ is homogeneous of polynomial degree $p$ provided $\theta=\sum f_{i} \partial_{x_{i}}$, where $f_{i} \in S_{p}$ for each $1 \leq i \leq \ell$. In this case we write pdeg $\theta=p$. Let $\operatorname{Der}_{S_{p}}$ be the $\mathbb{C}$-subspace of $\operatorname{Der}_{S}$ consisting of all homogeneous derivations of polynomial degree $p$. Then $\operatorname{Der}_{S}$ is a graded $S$-module, $\operatorname{Der}_{S}=\oplus_{p \in \mathbb{Z}} \operatorname{Der}_{S_{p}}$.

A hyperplane arrangement $\mathscr{A}$ in $V$ is a finite collection of hyperplanes in $V$. For a subspace $X$ of $V$, we have the associated localization of $\mathscr{A}$ at $X$ given by

$$
\mathscr{A}_{X}:=\{H \in \mathscr{A} \mid X \subseteq H\} \subseteq \mathscr{A} .
$$

Its rank is defined to be the codimension of $X$ in $V$.
Following Ziegler [Zie89], a multi-arrangement $(\mathscr{A}, \nu)$ is an arrangement $\mathscr{A}$ together with a multiplicity function $\nu: \mathscr{A} \rightarrow \mathbb{N}$ assigning to each hyperplane $H \in \mathscr{A}$ a multiplicity $\nu(H) \in \mathbb{N}$. If $\nu \equiv 1$, then $(\mathscr{A}, \nu)$ is called simple. We only consider central multiarrangements $(\mathscr{A}, \nu)$, i.e., $0 \in H$ for every $H \in \mathscr{A}$. In this case, we fix $\alpha_{H} \in V^{*}$ with $H=\operatorname{ker}\left(\alpha_{H}\right)$ for $H \in \mathscr{A}$. The order of $(\mathscr{A}, \nu)$ is given by

$$
|\nu|:=|(\mathscr{A}, \nu)|:=\sum_{H \in \mathscr{A}} \nu(H),
$$

and its defining polynomial $Q(\mathscr{A}, \nu) \in S$ is

$$
Q(\mathscr{A}, \nu):=\prod_{H \in \mathscr{A}} \alpha_{H}^{\nu(H)} .
$$

The module of derivations of $(\mathscr{A}, \nu)$ is defined by

$$
\mathfrak{D}(\mathscr{A}, \nu):=\left\{\theta \in \operatorname{Der}_{S} \mid \theta\left(\alpha_{H}\right) \in S \alpha_{H}^{\nu(H)} \text { for each } H \in \mathscr{A}\right\} .
$$

We say that $(\mathscr{A}, \nu)$ is free if $\mathfrak{D}(\mathscr{A}, \nu)$ is a free $S$-module [Zie89, Def. 6]. In this case, $\mathfrak{D}(\mathscr{A}, \nu)$ admits a basis $\left\{\theta_{1}, \ldots, \theta_{\ell}\right\}$ of $\ell$ homogeneous derivations [Zie89, Thm. 8]. While the $\theta_{i}$ 's are not unique, their polynomial degrees pdeg $\theta_{i}$ are. The multiset of these polynomial degrees is the set of exponents of the free multi-arrangement $(\mathscr{A}, \nu)$. It is denoted by

$$
\exp (\mathscr{A}, \nu):=\left\{\operatorname{pdeg}\left(\theta_{1}\right), \ldots, \operatorname{pdeg}\left(\theta_{\ell}\right)\right\} .
$$

Next we record Ziegler's analogue of Saito's criterion. The Saito matrix of $\theta_{1}, \ldots, \theta_{\ell} \in$ $\operatorname{Der}_{S}$ is given by

$$
M\left(\theta_{1}, \ldots, \theta_{\ell}\right):=\left[\begin{array}{ccc}
\theta_{1}\left(x_{1}\right) & \cdots & \theta_{1}\left(x_{\ell}\right) \\
\vdots & \ddots & \vdots \\
\theta_{\ell}\left(x_{1}\right) & \cdots & \theta_{\ell}\left(x_{\ell}\right)
\end{array}\right]
$$

see [OT92, Def. 4.11].
Theorem 2.1 ([Zie89, Thm. 8]). Let $(\mathscr{A}, \nu)$ be a multi-arrangement, and let $\theta_{1}, \ldots, \theta_{\ell} \in$ $\mathfrak{D}(\mathscr{A}, \nu)$. Then the following are equivalent:
(i) $\left\{\theta_{1}, \ldots, \theta_{\ell}\right\}$ is an $S$-basis of $\mathfrak{D}(\mathscr{A}, \nu)$.
(ii) $\operatorname{det} M\left(\theta_{1}, \ldots, \theta_{\ell}\right) \doteq Q(\mathscr{A}, \nu)$.

In particular, if each $\theta_{i}$ is homogeneous, then both are moreover equivalent to the following: (iii) $\theta_{1}, \ldots, \theta_{\ell}$ are linearly independent over $S$ and $\sum \operatorname{pdeg} \theta_{i}=\operatorname{deg} Q(\mathscr{A}, \nu)=|\nu|$.

In the statement and later on, the sign $\doteq$ denotes, as usual, equality up to a non-zero complex constant. Terao's celebrated Addition-Deletion Theorem [Ter80a] plays a crucial role in the study of free arrangements, see [OT92, Thm. 4.51]. We next describe its version for multi-arrangements from [ATW08]. Let $(\mathscr{A}, \nu)$ be a non-empty multi-arrangement, i.e., $|\nu| \geq 1$. Fix $H_{0}$ in $\mathscr{A}$ with $\nu\left(H_{0}\right) \geq 1$. Its deletion with respect to $H_{0}$ is given by $\left(\mathscr{A}^{\prime}, \nu^{\prime}\right)$, where $\nu^{\prime}\left(H_{0}\right)=\nu\left(H_{0}\right)-1$ and $\nu^{\prime}(H)=\nu(H)$ for all $H \neq H_{0}$. If $\nu^{\prime}\left(H_{0}\right)=0$, we set $\mathscr{A}^{\prime}=\mathscr{A} \backslash\left\{H_{0}\right\}$, and else set $\mathscr{A}^{\prime}=\mathscr{A}$. Its restriction with respect to $H_{0}$ is given by $\left(\mathscr{A}^{\prime \prime}, \nu^{*}\right)$, where $\mathscr{A}^{\prime \prime}=\left\{H \cap H_{0} \mid H \in \mathscr{A} \backslash\left\{H_{0}\right\}\right\}$. The Euler multiplicity $\nu^{*}$ of $\mathscr{A}^{\prime \prime}$ is defined as follows. Let $Y \in \mathscr{A}^{\prime \prime}$. Since the localization $\mathscr{A}_{Y}$ is of rank 2, the multiarrangement $\left(\mathscr{A}_{Y}, \nu_{Y}\right)$ is free where we set $\nu_{Y}=\left.\nu\right|_{Y}$ to be the restriction of $\nu$ to $\mathscr{A}_{Y}$ [Zie89, Cor. 7]. According to [ATW08, Prop. 2.1], the module of derivations $\mathfrak{D}\left(\mathscr{A}_{Y}, \nu_{Y}\right)$ admits a particular homogeneous basis $\left\{\theta_{Y}, \psi_{Y}, \partial_{3}, \ldots, \partial_{\ell}\right\}$, where $\theta_{Y}$ is identified by the property that $\theta_{Y} \notin \alpha_{0} \operatorname{Der}_{S}$ and $\psi_{Y}$ by the property that $\psi_{Y} \in \alpha_{0} \operatorname{Der}_{S}$, where $H_{0}=\operatorname{ker} \alpha_{0}$. Then the Euler multiplicity $\nu^{*}$ is defined on $Y$ as $\nu^{*}(Y)=\operatorname{pdeg} \theta_{Y}$. Crucial for our purpose is the fact that the value $\nu^{*}(Y)$ only depends on the $S$-module $\mathfrak{D}\left(\mathscr{A}_{Y}, \nu_{Y}\right)$. Sometimes, $(\mathscr{A}, \nu),\left(\mathscr{A}^{\prime}, \nu^{\prime}\right)$ and $\left(\mathscr{A}^{\prime \prime}, \nu^{*}\right)$ is referred to as the triple of multi-arrangements with respect to $H_{0}$.

Theorem 2.2 ([ATW08, Thm. 0.8]). Suppose that $(\mathscr{A}, \nu)$ is not empty, fix $H_{0}$ in $\mathscr{A}$ and let $(\mathscr{A}, \nu),\left(\mathscr{A}^{\prime}, \nu^{\prime}\right)$ and $\left(\mathscr{A}^{\prime \prime}, \nu^{*}\right)$ be the triple with respect to $H_{0}$. Then any two of the following statements imply the third:
(i) $(\mathscr{A}, \nu)$ is free with $\exp (\mathscr{A}, \nu)=\left\{b_{1}, \ldots, b_{\ell-1}, b_{\ell}\right\}$;
(ii) $\left(\mathscr{A}^{\prime}, \nu^{\prime}\right)$ is free with $\exp \left(\mathscr{A}^{\prime}, \nu^{\prime}\right)=\left\{b_{1}, \ldots, b_{\ell-1}, b_{\ell}-1\right\}$;
(iii) $\left(\mathscr{A}^{\prime \prime}, \nu^{*}\right)$ is free with $\exp \left(\mathscr{A}^{\prime \prime}, \nu^{*}\right)=\left\{b_{1}, \ldots, b_{\ell-1}\right\}$.

We need the following fact in the sequel.
Lemma 2.3 ([ATW08, Prop. 4.1(1)]). Let $H_{0} \in \mathscr{A}$. Suppose $X \in \mathscr{A}^{H_{0}}$ with $\mathscr{A}_{X}=$ $\left\{H_{0}, H\right\}$. For $\nu$ a multiplicity on $\mathscr{A}$, we have $\nu^{*}(X)=\nu(H)$.
2.2. Unitary Reflection Groups. Let $V \cong \mathbb{C}^{\ell}$, and consider a finite subgroup $W$ of $\mathrm{GL}(V)$. Then $W$ is a unitary reflection group if it is generated by its subset $\mathcal{R}=\mathcal{R}(W)$ of reflections, that is, the elements $r \in W$ for which the fixed space

$$
\operatorname{Fix}(r):=\operatorname{ker}(\mathbb{1}-r)=\{v \in V \mid r v=v\} \subseteq V
$$

is a hyperplane. We denote by $\mathscr{A}=\mathscr{A}(W)$ the associated reflection arrangement given by the collection of the reflecting hyperplanes. For $H \in \mathscr{A}$, let $W_{H}=\{w \in W \mid \operatorname{Fix}(w) \supseteq$ $H\}$ be the pointwise stabilizer of $H$ in $W$ and set $e_{H}=\left|W_{H}\right|$. Indeed, the elements in $W_{H}$ except the identity are exactly the reflections $r \in \mathcal{R}$ such that $\operatorname{Fix}(r)=H$, explaining the equality

$$
\begin{equation*}
|\mathcal{R}|+|\mathscr{A}|=\sum_{H \in \mathscr{A}} e_{H} \tag{2.4}
\end{equation*}
$$

Results of Shephard and Todd [ST54] and of Chevalley [Che55] distinguish unitary reflection groups as those finite subgroups of $\mathrm{GL}(V)$ for which the invariant subalgebra of the action on the symmetric algebra $S=S\left(V^{*}\right) \cong \mathbb{C}\left[x_{1}, \ldots, x_{\ell}\right]$ yields again a polynomial algebra,

$$
S^{W}=S\left(V^{*}\right)^{W} \cong \mathbb{C}\left[f_{1}, \ldots, f_{\ell}\right]
$$

While the basic invariants $f_{1}, \ldots, f_{\ell}$ are not unique, they can be chosen to be homogeneous, and then their degrees $d_{1} \leq \cdots \leq d_{\ell}$ are uniquely determined and called the degrees of $W$.

The group $W$ is called irreducible if it does not preserve a proper non-trivial subspace of $V$. It is well-known that such an irreducible reflection group can be generated either by $\ell$ or by $\ell+1$ reflections. An important subclass of irreducible unitary reflection groups are those that are well-generated, i.e., which can be generated by $\ell$ reflections. In particular, this subclass contains all (complexifications of) irreducible real reflection groups and all Shephard groups (symmetry groups of regular complex polytopes [OT92, Def. 6.119]).

Let $S_{+}^{W}$ denote the $W$-invariants without constant term, and let $\operatorname{Coinv}(W):=S / S_{+}^{W}$ be the ring of coinvariants of $W$. Observe that $\operatorname{Coinv}(W)$ is also a graded $W$-module, and indeed isomorphic to the regular representation of $W$, see [LT09, §4.4]. Thus, an irreducible representation $U$ in $\operatorname{Irr}(W)$ of dimension $d$ occurs $d$ times in $\operatorname{Coinv}(W)$ as a constituent. The $U$-exponents of $W$ are then given by the multiset of $d$ homogeneous degrees in the coinvariant algebra of $W$ in which $U$ appears,

$$
\exp _{U}(W)=\left\{n_{1}(U) \leq \ldots \leq n_{d}(U)\right\}
$$

In particular, $\exp (W)=\exp _{V}(W)$ are the exponents of $W$ and $\operatorname{coexp}(W)=\exp _{V^{*}}(W)$ are the coexponents of $W$. It is moreover well-known that the degrees of $W$ and the exponents are related by $d_{i}=n_{i}(V)+1$, implying

$$
\begin{equation*}
|\mathcal{R}|=\sum_{i=1}^{\ell} n_{i}(V) \tag{2.5}
\end{equation*}
$$

Terao showed in [Ter80b] that the reflection arrangement $\mathscr{A}$ of $W$ is free, and that the exponents of the arrangement coincide with the coexponents of $W$, cf. [OT92, Thm. 6.60],

$$
\exp \mathscr{A}=\operatorname{coexp}(W)
$$

Consequently, thanks to [OT92, Thm. 4.23], we have

$$
\begin{equation*}
|\mathscr{A}|=\sum_{i=1}^{\ell} n_{i}\left(V^{*}\right) \tag{2.6}
\end{equation*}
$$

The next definition can be found in [GG12]. The two equalities follow from (2.4), (2.5), and (2.6).

Definition 2.7. Let $W$ be an irreducible unitary reflection group. The Coxeter number $h=h_{W}$ is defined as

$$
h:=h_{W}:=\frac{1}{\ell} \sum_{H \in \mathscr{A}} e_{H}=\frac{1}{\ell}(|\mathcal{R}|+|\mathscr{A}|)=\frac{1}{\ell} \sum_{i=1}^{\ell}\left(n_{i}(V)+n_{i}\left(V^{*}\right)\right) .
$$

Remark 2.8. It was observed by Orlik and Solomon in [OS80, Thm. 5.5] that the group $W$ is well-generated if and only if the exponents and the coexponents pairwise sum up to the Coxeter number. This is,

$$
n_{i}(V)+n_{\ell+1-i}\left(V^{*}\right)=h
$$

for all $1 \leq i \leq \ell$. In this case, the Coxeter number $h=d_{\ell}=n_{\ell}(V)+1>d_{\ell-1}$ is the unique largest degree of a fundamental invariant, see [LT09, §12.6].

The fake degree of $U$ in $\operatorname{Irr}(W)$ of dimension $d$ is defined to be the polynomial

$$
f_{U}(q):=\sum_{i=1}^{d} q^{n_{i}(U)} \in \mathbb{N}[q],
$$

cf. [Mal99, Eq. (6.1)]. In [Mal99, Thm. 6.5], Malle showed that there is a permutation $\Psi$ of $\operatorname{Irr}(W)$ so that the fake degree polynomials $f_{U}(q)$ satisfy the semi-palindromic condition

$$
\begin{equation*}
f_{U}(q)=q^{h_{U}} f_{\Psi\left(U^{*}\right)}\left(q^{-1}\right) \tag{2.9}
\end{equation*}
$$

where

$$
\begin{equation*}
h_{U}:=|\mathcal{R}|-\sum_{r \in \mathcal{R}} \chi_{U}(r) / \chi_{U}(1) . \tag{2.10}
\end{equation*}
$$

Equivalently, $h_{U}$ is the integer by which the central element $\sum_{r \in \mathcal{R}}(\mathbb{1}-r) \in \mathbb{C}[W]$ acts on $U$. In particular, for any $U$ in $\operatorname{Irr}(W)$ of dimension $d$, we have

$$
n_{i}(U)+n_{d+1-i}\left(\Psi\left(U^{*}\right)\right)=h_{U}
$$

The following observations provide, for later reference, the formula in Theorem 1.2(ii) in a form analogous to the one used in [GG12, Sec. 3].

Lemma 2.11. The parameter $h_{U}$ defined in (2.10) satisfies $h_{U}=h_{U^{*}}$ and $h_{U}=h_{\Psi(U)}$. In particular, we have, for any $1 \leq i \leq \ell$ and any $m \in \mathbb{N}$,

$$
\begin{equation*}
m h+n_{i}\left(\Psi^{-m}\left(V^{*}\right)\right)=(m+1) h-n_{\ell+1-i}\left(\Psi^{-m-1}\left(V^{*}\right)^{*}\right) \tag{2.12}
\end{equation*}
$$

Proof. The equality $h_{U}=h_{U^{*}}$ is a direct consequences of (2.10). The equality $h_{U}=h_{\Psi(U)}$ follows, for example, from the description of $\Psi$ as the operator $\phi_{-\frac{1}{h},-1-\frac{1}{h}}^{i d}$ in [GG12, §2.12] together with the observation in [GG12, §2.8] that $h_{\phi_{-\frac{1}{h},-1-\frac{1}{h}}(U)}=h_{U}$. Plugging in $\Psi^{-m-1}\left(V^{*}\right)^{*}$ for the irreducible representation $U$ in (2.9) and using that $h_{\Psi^{-m-1}\left(V^{*}\right)^{*}}=$ $h_{V}=h$ yields (2.12).

See also [Opd00, Prop. 7.4] and [GG12, § 1.4] for further properties of the permutation $\Psi$ of $\operatorname{Irr}(W)$. Note that $\Psi$ is the identity permutation if and only if $W$ is wellgenerated [Mal99, Cor. 4.9].

We finally define the order multiplicity $\omega$ of the reflection arrangement $\mathscr{A}=\mathscr{A}(W)$ by $\omega(H)=e_{H}$ for $H \in \mathscr{A}$. In other words, the multiplicities are chosen so that the defining polynomial $Q(\mathscr{A}(W), \omega)$ of the multi-arrangement $(\mathscr{A}(W), \omega)$ is the discriminant of $W$, cf. [OT92, Def. 6.44],

$$
Q(\mathscr{A}(W), \omega)=\prod_{H \in \mathscr{A}(W)} \alpha_{H}^{e_{H}} .
$$

## 3. Proof of Theorem 1.1

In this section, we prove a strengthened version of Theorem 1.1. Our method is based on the approach by Yoshinaga [Yos02], also relying strongly on recent developments of flat systems of invariants for well-generated unitary reflection groups in the context of isomonodromic deformations and differential equations of Okubo type due to Kato, Mano and Sekiguchi [KMS16]. See Theorem 3.18 for the explicit formulation.

Let $\nabla: \operatorname{Der}_{S} \times \operatorname{Der}_{S} \rightarrow \operatorname{Der}_{S}$ be an affine connection. Recall that $\nabla$ is $S$-linear in the first parameter and $\mathbb{C}$-linear in the second, satisfying the Leibniz rule

$$
\nabla_{\delta}\left(p \delta^{\prime}\right)=\delta(p) \delta^{\prime}+p \nabla_{\delta}\left(\delta^{\prime}\right)
$$

for $\delta, \delta^{\prime} \in \operatorname{Der}_{S}$. The connection $\nabla$ is flat if $\nabla_{\delta}\left(\partial_{x_{i}}\right)=0$ for all $\delta \in \operatorname{Der}_{S}$, or, equivalently,

$$
\begin{equation*}
\nabla_{\delta}\left(\delta^{\prime}\right)=\sum_{i}\left(\delta p_{i}\right) \partial_{x_{i}} \tag{3.1}
\end{equation*}
$$

for $\delta, \delta^{\prime} \in \operatorname{Der}_{S}$ with $\delta^{\prime}=\sum p_{i} \partial_{x_{i}}$. Alternatively, this can be characterized by

$$
\begin{equation*}
\nabla_{\delta}\left(\delta^{\prime}\right)(\alpha)=\delta\left(\delta^{\prime}(\alpha)\right) \tag{3.2}
\end{equation*}
$$

for all $\alpha \in V^{*}$. Observe that for $\nabla$ flat and $\delta, \delta^{\prime}$ homogeneous, (3.1) implies that the derivation $\nabla_{\delta}\left(\delta^{\prime}\right)$ is again homogeneous with polynomial degree

$$
\begin{equation*}
\operatorname{pdeg}\left(\nabla_{\delta}\left(\delta^{\prime}\right)\right)=\operatorname{pdeg}(\delta)+\operatorname{pdeg}\left(\delta^{\prime}\right)-1 \tag{3.3}
\end{equation*}
$$

In the sequel, we largely follow the construction of flat systems of invariants as given in [KMS16, Sec. 6] in order to lift the constructions in [Yos02] to the well-generated case.

As before, we assume in this section that $W$ is an irreducible well-generated unitary reflection group. Let $F_{1}^{\mathrm{fl}}, \ldots, F_{\ell}^{\mathrm{fl}}$ be the special homogeneous fundamental invariants in $\mathbb{C}[\mathbf{x}]$ with $\mathbf{x}=\left(x_{1}, \ldots, x_{\ell}\right)$, as given in [KMS16, Thm. 6.1]. Recall that $\operatorname{deg}\left(F_{i}^{\mathrm{f}}\right)=d_{i}=$ $n_{i}(V)+1$ and $\mathbb{C}\left[F_{1}^{\mathrm{f}}, \ldots, F_{\ell}^{\mathrm{fl}}\right] \cong S^{W}$.

Consider indeterminates $\mathbf{t}=\left(t_{1}, \ldots, t_{\ell}\right)$ together with the map $t_{i} \mapsto F_{i}^{\mathrm{fl}}$ giving an isomorphism

$$
R:=\mathbb{C}[\mathrm{t}] \cong \mathbb{C}\left[F_{1}^{\mathrm{fl}}, \ldots, F_{\ell}^{\mathrm{fl}}\right] .
$$

Set moreover $\mathbb{C}\left[\mathbf{t}^{\prime}\right]:=\mathbb{C}\left[t_{1}, \ldots, t_{\ell-1}\right]$, its subring generated by $\mathbf{t}^{\prime}=\left(t_{1}, \ldots, t_{\ell-1}\right)$. In order to keep track of the information about the degrees of $F_{1}^{\mathrm{f}}, \ldots, F_{\ell}^{\mathrm{fl}}$, following [KMS16, Sec. 6], we define weights of the variables $t_{i}$ by

$$
\mathrm{w}\left(t_{i}\right):=\operatorname{deg}\left(F_{i}^{\mathrm{f}}\right) / h=d_{i} / h=\left(n_{i}(V)+1\right) / h .
$$

As usual, set

$$
J_{\partial \mathbf{t} / \partial \mathbf{x}}:=\left(\begin{array}{c}
\partial_{x_{1}} \\
\vdots \\
\partial_{x_{\ell}}
\end{array}\right)\left(t_{1}, \ldots, t_{\ell}\right)=\left[\begin{array}{ccc}
\partial t_{1} / \partial x_{1} & \cdots & \partial t_{\ell} / \partial x_{1} \\
\vdots & \ddots & \vdots \\
\partial t_{1} / \partial x_{\ell} & \cdots & \partial t_{\ell} / \partial x_{\ell}
\end{array}\right] \in \mathbb{C}[\mathbf{x}]^{\ell \times \ell}
$$

with inverse matrix $J_{\partial \mathbf{x} / \partial \mathbf{t}}:=J_{\partial \mathbf{t} / \partial \mathbf{x}}^{-1}=\left(\partial_{t_{1}}, \ldots, \partial_{t_{\ell}}\right)^{\operatorname{tr}}\left(x_{1}, \ldots, x_{\ell}\right)$. It is well-known that $\operatorname{det} J_{\partial \mathrm{t} / \partial \mathbf{x}} \doteq \prod_{H \in \mathscr{A}} \alpha_{H}^{e_{H}-1}$, see [OT92, Thm. 6.42].

The primitive vector field

$$
D:=\partial_{8}^{t_{\ell}} \in \operatorname{Der}_{R}
$$

is given by

$$
D=\operatorname{det} J_{\partial \mathbf{x} / \partial \mathbf{t}}\left|\begin{array}{cccc}
\frac{\partial t_{1}}{\partial x_{1}} & \cdots & \frac{\partial t_{\ell-1}}{\partial x_{1}} & \frac{\partial}{\partial x_{1}} \\
\vdots & \ddots & \vdots & \vdots \\
\frac{\partial t_{1}}{\partial x_{\ell}} & \cdots & \frac{\partial t_{\ell-1}}{\partial x_{\ell}} & \frac{\partial}{\partial x_{\ell}}
\end{array}\right|,
$$

implying in particular that $D$ is homogeneous with

$$
\begin{equation*}
\operatorname{pdeg}(D)=-n_{\ell}(V)=-(h-1) \tag{3.4}
\end{equation*}
$$

when considered inside $\sum \mathbb{C}(\mathbf{x}) \partial_{x_{i}}$. We have seen in Remark 2.8 that $h=d_{\ell}>d_{\ell-1}$. The primitive vector field $D$ is thus, up to a non-zero complex constant, independent of the given choice of fundamental invariants.

Consider $X:=V / W=\operatorname{spec}(\mathbb{C}[\mathbf{t}])$ and let $\Delta(\mathbf{t})$ be the discriminant of $W$ given by

$$
\Delta\left(F_{1}^{\mathrm{f}}(\mathbf{x}), \ldots, F_{\ell}^{\mathrm{f}}(\mathbf{x})\right)=\prod_{H \in \mathscr{A}} \alpha_{H}^{e_{H}}
$$

with vanishing locus $\mathcal{H}:=\{\bar{p} \in X \mid \Delta(\bar{p})=0\}$, cf. [OT92, Def. 6.44]. Let $\operatorname{Der}_{R}$ be the $R$-module of logarithmic vector fields, and let

$$
\operatorname{Der}_{R}(-\log \Delta):=\left\{\theta \in \operatorname{Der}_{R} \mid \theta \Delta \in R \Delta\right\}
$$

be the module of logarithmic vector fields along $\mathcal{H}$. We have an $R$-isomorphism between such logarithmic vector fields and $W$-invariant $S$-derivations,

$$
\begin{equation*}
\operatorname{Der}_{R}(-\log \Delta) \cong \operatorname{Der}_{S}^{W}, \tag{3.5}
\end{equation*}
$$

and $\operatorname{Der}_{R}(-\log \Delta)$ is a free $R$-module, cf. [OT92, Cor. 6.58].
Bessis showed in [Bes15, Thm. 2.4] that there exists a system of flat homogeneous derivations $\left\{\xi_{1}, \ldots, \xi_{\ell}\right\}$ of $\operatorname{Der}_{R}(-\log \Delta)$. This means, its Saito matrix

$$
M_{\xi}:=M\left(\xi_{\ell}, \ldots, \xi_{1}\right)=\left[\begin{array}{ccc}
\xi_{\ell}\left(t_{1}\right) & \cdots & \xi_{\ell}\left(t_{\ell}\right) \\
\vdots & \ddots & \vdots \\
\xi_{1}\left(t_{1}\right) & \cdots & \xi_{1}\left(t_{\ell}\right)
\end{array}\right]
$$

decomposes as

$$
\begin{equation*}
M_{\xi}=t_{\ell} \mathbb{1}_{\ell}+M^{(0)}\left(\mathbf{t}^{\prime}\right) \tag{3.6}
\end{equation*}
$$

with $M^{(0)}\left(\mathbf{t}^{\prime}\right) \in \mathbb{C}\left[\mathbf{t}^{\prime}\right]^{\ell \times \ell}$. As before, we have $\left(\xi_{\ell}, \ldots, \xi_{1}\right)^{\operatorname{tr}}=M_{\xi}\left(\partial_{t_{1}}, \ldots, \partial_{t_{\ell}}\right)^{\mathrm{tr}}$. Moreover, we obtain that $\Delta(\mathbf{t})$ is a monic polynomial in $t_{\ell}$ with coefficients in $\mathbb{C}\left[\mathbf{t}^{\prime}\right]$, i.e.,

$$
\Delta(\mathbf{t})=t_{\ell}^{\ell}+a_{\ell-1}\left(\mathbf{t}^{\prime}\right) t_{\ell}^{\ell-1}+\ldots+a_{1}\left(\mathbf{t}^{\prime}\right) t_{\ell}+a_{0}\left(\mathbf{t}^{\prime}\right)
$$

As observed in [KMS16, Lem. 3.12], such a system of flat homogeneous derivations is unique. Following [KMS16, Eqs. (52), (53)], where this flat system is denoted by $\left(V_{\ell}, \ldots, V_{1}\right)$, we have

$$
\mathrm{w}\left(\xi_{\ell+1-j}\left(t_{i}\right)\right)=1-\mathrm{w}\left(t_{j}\right)+\mathrm{w}\left(t_{i}\right)
$$

and

$$
\xi_{1}=\sum \mathrm{w}\left(t_{i}\right) t_{i} \partial_{t_{i}} \in \operatorname{Der}_{R}
$$

is the Euler vector field mapped to the Euler derivation

$$
\begin{equation*}
E:=\sum x_{i} \partial_{x_{i}} \in \operatorname{Der}_{S}^{W} \tag{3.7}
\end{equation*}
$$

under the isomorphism in (3.5). As described in [KMS16, Lem. 3.9], one decomposes

$$
\begin{equation*}
M_{\xi}=\sum_{9} \mathrm{w}\left(t_{i}\right) t_{i} \tilde{B}^{(i)} \tag{3.8}
\end{equation*}
$$

and defines the weighted homogeneous $(\ell \times \ell)$-matrix $C(\mathbf{t})$ such that

$$
\begin{equation*}
\tilde{B}^{(i)}=\partial C / \partial t_{i} \quad \text { and } \quad \xi_{1} C=M_{\xi} . \tag{3.9}
\end{equation*}
$$

In this case, [KMS16, Thm. 6.1] yields that $t_{i}=C_{\ell, i}$ and thus, $\mathbf{t}$ is a flat coordinate system on $X$ associated to the Okubo type differential equation

$$
\begin{equation*}
d Y=-M_{\xi}^{-1} d C B_{\infty} Y \tag{3.10}
\end{equation*}
$$

where $B_{\infty}$ is the diagonal matrix

$$
B_{\infty}:=\operatorname{diag}\left(\mathrm{w}\left(t_{i}\right)-(h+1) / h\right)=\operatorname{diag}\left(\left(d_{i}-h-1\right) / h\right),
$$

and

$$
Y:=-B_{\infty}^{-1}\left(\xi_{\ell}, \ldots, \xi_{1}\right)^{\operatorname{tr}}\left(x_{1}, \ldots, x_{\ell}\right)=-B_{\infty}^{-1} M_{\xi} J_{\partial \mathbf{x} / \partial \mathrm{t}} .
$$

Define a connection $\nabla$ on $\operatorname{Der}_{R}$ by

$$
\nabla\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right)=-M_{\xi}^{-1}(\mathbf{t}) d C(\mathbf{t})\left(B_{\infty}+\mathbb{1}_{\ell}\right)\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right)
$$

where $d C=\sum \tilde{B}^{(i)} d t_{i}$ is the differential of the matrix $C(\mathbf{t})$ as given in (3.9).
Proposition 3.11. The connection $\nabla$ extends to a connection on $\operatorname{Der}_{S}$ which is flat, i.e.,

$$
\nabla\left(\begin{array}{c}
\partial_{x_{1}} \\
\vdots \\
\partial_{x_{\ell}}
\end{array}\right)=0
$$

Proof. Using the definition of $\nabla$ and the Leibniz rule, we obtain

$$
\begin{align*}
\nabla\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right) & =d J_{\partial \mathbf{x} / \partial \mathrm{t}}\left(\begin{array}{c}
\partial_{x_{1}} \\
\vdots \\
\partial_{x_{\ell}}
\end{array}\right)+J_{\partial \mathbf{x} / \partial \mathrm{t}} \nabla\left(\begin{array}{c}
\partial_{x_{1}} \\
\vdots \\
\partial_{x_{\ell}}
\end{array}\right)  \tag{3.12}\\
& =-M_{\xi}^{-1} d C\left(B_{\infty}+\mathbb{1}_{\ell}\right) J_{\partial \mathbf{x} / \partial \mathrm{t}}\left(\begin{array}{c}
\partial_{x_{1}} \\
\vdots \\
\partial_{x_{\ell}}
\end{array}\right) .
\end{align*}
$$

By (3.10), we have

$$
\begin{align*}
d Y & =-B_{\infty}^{-1}\left(d M_{\xi} J_{\partial \mathbf{x} / \partial \mathbf{t}}+M_{\xi} d J_{\partial \mathbf{x} / \partial \mathbf{t}}\right) \\
& =-M_{\xi}^{-1} d C B_{\infty} Y  \tag{3.13}\\
& =d C J_{\partial \mathbf{x} / \partial \mathbf{t}},
\end{align*}
$$

where all $\tilde{B}^{(i)}$ and $M_{\xi}$ mutually commute, according to [KMS16, Eq. (13)]. Thanks to [KMS16, Eq. (28)], we have

$$
d M_{\xi}=d C+\left[d C, B_{\infty}\right] .
$$

The identity (3.13) then implies

$$
\begin{align*}
-M_{\xi} d J_{\partial \mathbf{x} / \partial \mathbf{t}} & =B_{\infty} d C J_{\partial \mathbf{x} / \partial \mathbf{t}}+\left(d C+\left[d C, B_{\infty}\right]\right) J_{\partial \mathbf{x} / \partial \mathbf{t}} \\
& =d C\left(B_{\infty}+\mathbb{1}_{\ell}\right) J_{\partial \mathbf{x} / \partial \mathbf{t}} \tag{3.14}
\end{align*}
$$

We finally deduce from (3.12) and (3.14) that

$$
J_{\partial \mathbf{x} / \partial \mathrm{t}} \nabla\left(\begin{array}{c}
\partial_{x_{1}} \\
\vdots \\
\partial_{x_{\ell}}
\end{array}\right)=-\left(M_{\xi}^{-1} d C\left(B_{\infty}+\mathbb{1}_{\ell}\right) J_{\partial \mathbf{x} / \partial \mathrm{t}}+d J_{\partial \mathbf{x} / \partial \mathrm{t}}\right)\left(\begin{array}{c}
\partial_{x_{1}} \\
\vdots \\
\partial_{x_{\ell}}
\end{array}\right)=0
$$

Since $J_{\partial \mathbf{x} / \partial \mathrm{t}}$ is invertible, the result follows.
One further main ingredient in the proof of Theorem 1.1 is the following proposition.
Proposition 3.15. We have $\mathbb{C}\left[\boldsymbol{t}^{\prime}\right]$-isomorphisms

$$
\begin{array}{r}
\nabla_{D}: \operatorname{Der}_{R}(-\log \Delta) \longrightarrow \operatorname{Der}_{R} \\
\nabla_{D}^{-1}: \operatorname{Der}_{R} \longrightarrow \operatorname{Der}_{R}(-\log \Delta)
\end{array}
$$

given by

$$
\begin{align*}
\nabla_{D}\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right) & =-M_{\xi}^{-1}\left(B_{\infty}+\mathbb{1}_{\ell}\right)\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right)  \tag{3.16}\\
\nabla_{D}^{-1}\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right) & =-B_{\infty}^{-1}\left(\begin{array}{c}
\xi_{\ell} \\
\vdots \\
\xi_{1}
\end{array}\right)=-B_{\infty}^{-1} M_{\xi}\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right) .
\end{align*}
$$

Proof. The first equation in (3.16) is a direct consequence of the fact that $\tilde{B}^{(\ell)}=\mathbb{1}_{\ell}$ which follows from (3.8) in light of (3.6). On the other hand, we have

$$
\begin{aligned}
\nabla_{D}\left(\begin{array}{c}
\xi_{\ell} \\
\vdots \\
\xi_{1}
\end{array}\right) & =\nabla_{D}\left(M_{\xi}\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right)\right) \\
& =\frac{\partial M_{\xi}}{\partial t_{\ell}}\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right)+M_{\xi} \nabla_{D}\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right) \\
& =\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right)-\left(B_{\infty}+\mathbb{1}_{\ell}\right)\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right) \\
& =-B_{\infty}\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right),
\end{aligned}
$$

where we used that $\frac{\partial M_{\xi}}{\partial t_{\ell}}=\mathbb{1}_{\ell}$, see again (3.6). Recall that $\left\{\xi_{1}, \ldots, \xi_{\ell}\right\}$ is a basis of $\operatorname{Der}_{R}(-\log \Delta)$ and one directly calculates that $\nabla_{D}$ is $\mathbb{C}\left[\mathbf{t}^{\prime}\right]$-linear. We thus obtain that $\nabla_{D}: \operatorname{Der}_{R}(-\log \Delta) \longrightarrow \operatorname{Der}_{R}$ is a $\mathbb{C}\left[\mathbf{t}^{\prime}\right]$-isomorphism with inverse

$$
\nabla_{D}^{-1}\left(\begin{array}{c}
\partial_{t_{1}} \\
\vdots \\
\partial_{t_{\ell}}
\end{array}\right)=-B_{\infty}^{-1}\left(\begin{array}{c}
\xi_{\ell} \\
\vdots \\
\xi_{1}
\end{array}\right) .
$$

This completes the proof of the proposition.
With Proposition 3.15 in hand, we obtain an explicit formula for computing $\nabla_{D}^{-1}$ as follows.

Corollary 3.17. We have that $\nabla_{D}^{-1}: \operatorname{Der}_{R} \longrightarrow \operatorname{Der}_{R}(-\log \Delta)$ is given by the linearity in $\mathbb{C}\left[t^{\prime}\right]$ and the inductive formula

$$
\nabla_{D}^{-1}\left(t_{\ell}^{k} \partial_{t_{i}}\right)=\frac{h}{(k+1) h+1-d_{i}}\left(t_{\ell}^{k} \xi_{\ell+1-i}-k \sum_{j=1}^{\ell}\left[M^{(0)}\left(\boldsymbol{t}^{\prime}\right)\right]_{i j} \nabla_{D}^{-1}\left(t_{\ell}^{k-1} \partial_{t_{j}}\right)\right)
$$

for $k \in \mathbb{N}_{+}$with base case $k=0$ as given in (3.16). Here $M^{(0)}\left(\boldsymbol{t}^{\prime}\right)=M_{\xi}-t_{\ell} \mathbb{1}_{\ell}$ is as in (3.6).

Proof. Recall that $\left(\xi_{\ell}, \ldots, \xi_{1}\right)^{\mathrm{tr}}=M_{\xi}\left(\partial_{t_{1}}, \ldots, \partial_{t_{\ell}}\right)^{\mathrm{tr}}$. The computation

$$
\begin{aligned}
\nabla_{D}\left(t_{\ell}^{k} \xi_{\ell+1-i}\right) & =k t_{\ell}^{k-1} \xi_{\ell+1-i}+t_{\ell}^{k} \nabla_{D}\left(\xi_{\ell+1-i}\right) \\
& =k t_{\ell}^{k-1}\left(t_{\ell} \partial_{t_{i}}+\sum_{j=1}^{\ell}\left[M^{(0)}\left(\mathbf{t}^{\prime}\right)\right]_{i j} \partial_{t_{j}}\right)+\frac{h+1-d_{i}}{h} t_{\ell}^{k} \partial_{t_{i}} \\
& =\frac{(k+1) h+1-d_{i}}{h} t_{\ell}^{k} \partial_{t_{i}}+k \sum_{j=1}^{\ell}\left[M^{(0)}\left(\mathbf{t}^{\prime}\right)\right]_{i j} t_{\ell}^{k-1} \partial_{t_{j}}
\end{aligned}
$$

implies that

$$
t_{\ell}^{k} \partial_{t_{i}}=\frac{h}{(k+1) h+1-d_{i}}\left(\nabla_{D}\left(t_{\ell}^{k} \xi_{\ell+1-i}\right)-k \sum_{j=1}^{\ell}\left[M^{(0)}\left(\mathbf{t}^{\prime}\right)\right]_{i j} t_{\ell}^{k-1} \partial_{t_{j}}\right)
$$

where we used that $(k+1) h+1-d_{i}>0$. Applying $\nabla_{D}^{-1}$ to both sides and using that it is $\mathbb{C}\left[\mathbf{t}^{\prime}\right]$-linear yields the claim.

The following is our generalization of [Yos02, Thm. 7] to the well-generated setting. Recall the Euler derivation $E$ from (3.7).

Theorem 3.18. Let $W$ be an irreducible, well-generated unitary reflection group with reflection arrangement $\mathscr{A}$. Let $\omega: \mathscr{A} \rightarrow \mathbb{N}$ given by $\omega(H)=e_{H}$, and let $m \in \mathbb{N}$. Suppose that $\mu: \mathscr{A} \rightarrow\{0,1\}$ such that $\mathfrak{D}(\mathscr{A}, \mu)$ is free with homogeneous basis $\theta_{1}, \ldots, \theta_{\ell}$. Then $\mathfrak{D}(\mathscr{A}, m \omega+\mu)$ is free with basis

$$
\nabla_{\theta_{1}} \nabla_{D}^{-m}(E), \ldots, \nabla_{\theta_{\ell}} \nabla_{D}^{-m}(E) .
$$

Moreover,

$$
\exp (\mathscr{A}, m \omega+\mu)=\left\{m h+\operatorname{pdeg}\left(\theta_{1}\right), \ldots, m h+\operatorname{pdeg}\left(\theta_{\ell}\right)\right\} .
$$

Armed with Theorem 3.18, we derive our first main theorem.
Proof of Theorem 1.1. One obtains the two statements in the theorem from the special cases in Theorem 3.18 with $\mu \equiv 0$ and $\mu \equiv 1$. Freeness in the first case is trivial, and is due to Terao [Ter80b] in the second.
Proof of Theorem 3.18. Let $\delta \in \operatorname{Der}_{S}$ and $\alpha=\alpha_{H}$ with $H \in \mathscr{A}$. We first show that, for any $m \in \mathbb{N}$,

$$
\begin{equation*}
\nabla_{D}(\delta) \alpha \in \alpha^{m} S \quad \Longleftrightarrow \quad \delta \alpha \in \alpha^{m+e_{H}} S \tag{3.19}
\end{equation*}
$$

For the reverse implication, suppose that $\delta \alpha=\alpha_{H}^{k+e_{H}} f$ for some $f \in S$ and $k \in \mathbb{N}$. We then obtain from (3.2) that

$$
\nabla_{D}(\delta) \alpha=D(\delta \alpha) \doteq \operatorname{det} J_{\partial \mathbf{x} / \partial \mathbf{t}}\left|\begin{array}{cccc}
\frac{\partial t_{1}}{\partial x_{1}} & \cdots & \frac{\partial t_{\ell-1}}{\partial x_{1}} & \frac{\partial \alpha^{k+e_{H}}}{\partial x_{1}} \\
\vdots & \ddots & \vdots & \vdots \\
\frac{\partial t_{1}}{\partial x_{\ell}} & \cdots & \frac{\partial t_{\ell-1}}{\partial x_{\ell}} & \frac{\partial \alpha^{k+e_{H}}}{\partial x_{\ell}}
\end{array}\right|
$$

It now follows from the product rule for derivations that $\nabla_{D}(\delta) \alpha$ is divisible by $\alpha^{k}$.
For the forward implication, assume that $k$ is maximal such that $\delta \alpha=\alpha^{k+e_{H}} f$. We show that in this case, $\nabla_{D}(\delta) \alpha \notin \alpha^{k+1} S$. We may assume, after a possible change of basis, that $\alpha=x_{\ell}$. Since $\operatorname{det} J_{\partial \mathbf{x} / \partial \mathbf{t}}=\operatorname{det} J_{\partial \mathbf{t} / \partial \mathbf{x}}^{-1}=\left(\prod_{H \in \mathscr{A}} \alpha_{H}^{e_{H}-1}\right)^{-1}$, we have to show that the maximal minor

$$
\left|\begin{array}{ccc}
\frac{\partial t_{1}}{\partial x_{1}} & \cdots & \frac{\partial t_{\ell-1}}{\partial x_{1}}  \tag{3.20}\\
\vdots & \ddots & \vdots \\
\frac{\partial t_{1}}{\partial x_{\ell-1}} & \cdots & \frac{\partial t_{\ell-1}}{\partial x_{\ell-1}}
\end{array}\right|
$$

is not divisible by $\alpha$. This follows from a variant of the argument in the proof of [OT92, Lem. 6.41]. Arguing as in loc. cit., the sequence $\left(h_{1}, \ldots, h_{\ell}\right)=\left(t_{1}(\mathbf{x}), \ldots, t_{\ell-1}(\mathbf{x}), x_{\ell}\right)$ is regular. Because the considered determinant equals

$$
\left|\begin{array}{cccc}
\frac{\partial t_{1}}{\partial x_{1}} & \cdots & \frac{\partial t_{\ell-1}}{\partial x_{1}} & \frac{\partial x_{\ell}}{\partial x_{1}} \\
\vdots & \ddots & \vdots & \vdots \\
\frac{\partial t_{1}}{\partial x_{\ell-1}} & \cdots & \frac{\partial t_{\ell-1}}{\partial x_{\ell-1}} & \frac{\partial x_{\ell}}{\partial x_{\ell-1}} \\
\frac{\partial t_{1}}{\partial x_{\ell}} & \cdots & \frac{\partial t_{\ell-1}}{\partial x_{\ell}} & \frac{\partial x_{\ell}}{\partial x_{\ell}}
\end{array}\right|
$$

applying loc. cit. directly shows that this determinant does not belong to the ideal generated by $\left(t_{1}(\mathbf{x}), \ldots, t_{\ell-1}(\mathbf{x}), x_{\ell}\right)$. In particular, the determinant is not divisible by $x_{\ell}=\alpha$, as desired.

Next, observe that (3.19) and Proposition 3.15 immediately imply

$$
\delta \alpha \in \alpha^{k} S \quad \Longleftrightarrow \quad \nabla_{D}^{-1}(\delta) \alpha \in \alpha^{k+e_{H}} S
$$

for $\delta \in \operatorname{Der}_{R}$, forcing $\nabla_{D}^{-m}(E) \alpha=\alpha^{m e_{H}+1} f$ for some $f \in S$. Thus, applying $\nabla_{\theta}$ for $\theta \in \mathfrak{D}(\mathscr{A}, \mu)$ to both sides and using (3.2) entails

$$
\nabla_{\theta} \nabla_{D}^{-m}(E) \alpha=\alpha^{m e_{H}}\left(\left(m e_{H}+1\right)(\theta \alpha) f+\alpha(\theta(f))\right.
$$

As $\theta \alpha$ is divisible by $\alpha^{\mu(H)}$ and $0 \leq \mu(H) \leq 1$, we obtain that $\nabla_{\theta} \nabla_{D}^{-m}(E) \alpha$ is divisible by $\alpha^{m e_{H}+\mu(H)}$, implying that

$$
\nabla_{\theta} \nabla_{D}^{-m}(E) \in \mathfrak{D}(\mathscr{A}, m \omega+\mu) .
$$

For $\theta \in \mathfrak{D}(\mathscr{A}, \mu)$ homogeneous, we obtain from (3.3) and (3.4) that $\nabla_{\theta} \nabla_{D}^{-m}(E)$ is homogeneous as well with

$$
\operatorname{pdeg}\left(\nabla_{\theta} \nabla_{D}^{-m}(E)\right)=m h+\operatorname{pdeg} \theta
$$

Let now $\theta_{1}, \ldots, \theta_{\ell}$ be the given homogeneous basis of $\mathfrak{D}(\mathscr{A}, \mu)$. Then, since $\sum \operatorname{pdeg}\left(\theta_{i}\right)=$ $|\mu|$, we immediately get

$$
\sum_{i=1}^{\ell} \operatorname{pdeg}\left(\nabla_{\theta_{i}} \nabla_{D}^{-m}(E)\right)=m h \ell+|\mu|=|m \omega+\mu|
$$

The statement then follows with Theorem 2.1(iii).
3.1. An example. We finish this section with a detailed example of the computation of the basis for $\mathfrak{D}(\mathscr{A}(W), \omega)$ with $W=G(3,1,2)$. In this cases, the degrees are

$$
d_{1}=3, \quad d_{2}=h=6 .
$$

We refer to [KMS16, Rem. 6.2] for a general strategy how to compute a flat system of invariants from the potential vector field corresponding to the Okubo type differential equation (3.10) as defined in [KMS16, Def 4.2]. Such have been computed in many types in [AL16], see also [KMS15].

Given such a potential vector field $\vec{g}=\left(g_{1}(\mathbf{t}), \ldots, g_{\ell}(\mathbf{t})\right)$ and a flat system of invariants $F_{1}^{\mathrm{f}}(\mathbf{x}), \ldots, F_{\ell}^{\mathrm{f}}(\mathbf{x})$, the general strategy is as follows:
(1) Compute $\tilde{B}^{(i)}$ using $\left[\tilde{B}^{(i)}\right]_{j k}=\frac{\partial^{2} g_{k}}{\partial t_{i} \partial t_{j}}$, as given in the proof of [KMS16, Prop. 4.4].
(2) Compute $M_{\xi}=\sum \mathrm{w}\left(t_{i}\right) t_{i} \tilde{B}^{(i)}$, as given in (3.8).
(3) Compute $\nabla_{D}^{-m}(E) \in \operatorname{Der}_{R}(-\log \Delta)$, using Proposition 3.15 and Corollary 3.17.
(4) Transfer $\nabla_{D}^{-m}(E) \in \operatorname{Der}_{R}(-\log \Delta)$ into $\nabla_{D}^{-m}(E) \in \operatorname{Der}_{S}^{W}$ by specializing $t_{i} \mapsto F_{i}^{\mathrm{f}}(\mathbf{x})$ and using

$$
\left(\partial_{t_{1}}, \ldots, \partial_{t_{\ell}}\right)^{\operatorname{tr}}=J_{\partial \mathbf{x} / \partial \mathbf{t}}\left(\partial_{x_{1}}, \ldots, \partial_{x_{\ell}}\right)^{\mathrm{tr}} .
$$

(5) Given a homogeneous basis $\theta_{1}, \ldots, \theta_{\ell}$ of $\mathfrak{D}(\mathscr{A}, \mu)$ for some $\mu: \mathscr{A} \rightarrow\{0,1\}$, one finally uses Proposition 3.11 to compute the homogeneous basis of $\mathfrak{D}(\mathscr{A}, m \omega+\mu)$.

Following [AL16, Sec. 5.17] for $G(3,1,2)$, the potential vector field $\vec{g}=\left(g_{1}(\mathbf{t}), g_{2}(\mathbf{t})\right)$ is given by

$$
g_{1}(\mathbf{t})=\frac{1}{18} t_{1}^{3}+t_{1} t_{2}, \quad g_{2}(\mathbf{t})=\frac{1}{54} t_{1}^{4}+\frac{1}{2} t_{2}^{2}
$$

and a flat system of fundamental invariants is given by

$$
F_{1}^{\mathrm{f}}(\mathbf{x})=x_{1}^{3}+x_{2}^{3}, \quad F_{2}^{\mathrm{f}}(\mathbf{x})=\frac{1}{6} x_{1}^{6}-\frac{5}{3} x_{1}^{3} x_{2}^{3}+\frac{1}{6} x_{2}^{6} .
$$

First, we obtain from the degrees that

$$
-B_{\infty}=\left[\begin{array}{cc}
\frac{2}{3} & 0 \\
0 & \frac{1}{6}
\end{array}\right] .
$$

From the potential vector field, we compute

$$
\tilde{B}^{(1)}=\left[\begin{array}{cc}
\frac{1}{3} t_{1} & \frac{2}{9} t_{1}^{2} \\
1 & 0
\end{array}\right], \quad \tilde{B}^{(2)}=\left[\begin{array}{ll}
1 & 0 \\
0 & 1
\end{array}\right]
$$

implying

$$
M_{\xi}=\frac{1}{2} t_{1} \tilde{B}^{(1)}+t_{2} \tilde{B}^{(2)}=\left[\begin{array}{cc}
\frac{1}{6} t_{1}^{2}+t_{2} & \frac{1}{9} t_{1}^{3} \\
\frac{1}{2} t_{1} & t_{2} .
\end{array}\right]
$$

Next, we compute

$$
\nabla_{D}^{-1}\binom{\partial_{t_{1}}}{\partial_{t_{2}}}=-B_{\infty}^{-1} M_{\xi}\binom{\partial_{t_{1}}}{\partial_{t_{2}}}=\left[\begin{array}{cc}
\frac{1}{4} t_{1}^{2}+\frac{3}{2} t_{2} & \frac{1}{6} t_{1}^{3} \\
3 t_{1} & 6 t_{2}
\end{array}\right]\binom{\partial_{t_{1}}}{\partial_{t_{2}}}
$$

and

$$
\begin{aligned}
\nabla_{D}^{-1}\left(t_{2} \partial_{t_{2}}\right) & =\frac{6}{7}\left(t_{2} \xi_{1}-\left(\left[M^{(0)}\right]_{21} \nabla_{D}^{-1}\left(\partial_{t_{1}}\right)+\left[M^{(0)}\right]_{22} \nabla_{D}^{-1}\left(\partial_{t_{2}}\right)\right)\right) \\
& =\frac{6}{7}\left(t_{2}\left(\frac{1}{2} t_{1} \partial_{t_{1}}+t_{2} \partial_{t_{2}}\right)-\frac{1}{2} t_{1} \nabla_{D}^{-1}\left(\partial_{t_{1}}\right)\right) \\
& =\frac{3}{7} t_{1} t_{2} \partial_{t_{1}}+\frac{6}{7} t_{2}^{2} \partial_{t_{2}}-\frac{3}{7} t_{1}\left(\left(\frac{1}{4} t_{1}^{2}+\frac{3}{2} t_{2}\right) \partial_{t_{1}}+\frac{1}{6} t_{1}^{3} \partial_{t_{2}}\right) \\
& =-\left(\frac{3}{28} t_{1}^{3}+\frac{3}{14} t_{1} t_{2}\right) \partial_{t_{1}}+\left(\frac{6}{7} t_{2}^{2}-\frac{1}{14} t_{1}^{4}\right) \partial_{t_{2}} .
\end{aligned}
$$

Therefore, we have

$$
\begin{aligned}
\nabla_{D}^{-1}(E) & =\nabla_{D}^{-1}\left(\frac{1}{2} t_{1} \partial_{t_{1}}+t_{2} \partial_{t_{2}}\right) \\
& =\frac{1}{2} t_{1} \nabla_{D}^{-1}\left(\partial_{t_{1}}\right)+\nabla_{D}^{-1}\left(t_{2} \partial_{t_{2}}\right) \\
& =\frac{1}{2} t_{1}\left(\left(\frac{1}{4} t_{1}^{2}+\frac{3}{2} t_{2}\right) \partial_{t_{1}}+\frac{1}{6} t_{1}^{3} \partial_{t_{2}}\right)-\left(\frac{3}{28} t_{1}^{3}+\frac{3}{14} t_{1} t_{2}\right) \partial_{t_{1}}+\left(\frac{6}{7} t_{2}^{2}-\frac{1}{14} t_{1}^{4}\right) \partial_{t_{2}} \\
& =\left(\frac{1}{5} t_{1}^{3}+\frac{15}{28} t_{1} t_{2}\right) \partial_{t_{1}}+\left(\frac{1}{84} t_{1}^{4}+\frac{6}{7} t_{2}^{2}\right) \partial_{t_{2}} \in \operatorname{Der}_{R}(-\log \Delta) .
\end{aligned}
$$

We next compute

$$
J_{\partial \mathbf{t} / \partial \mathbf{x}}=\left[\begin{array}{cc}
3 x_{1}^{2} & x_{1}^{5}-5 x_{1}^{2} x_{2}^{3} \\
3 x_{2}^{2} & -5 x_{1}^{3} x_{2}^{2}+x_{2}^{5}
\end{array}\right], \quad \operatorname{det} J_{\partial \mathbf{t} / \partial \mathbf{x}}=-18 x_{1}^{5} x_{2}^{2}+18 x_{1}^{2} x_{2}^{5}
$$

and

$$
J_{\partial \mathbf{x} / \partial \mathbf{t}}=J_{\partial \mathbf{t} / \partial \mathbf{x}}^{-1}=\operatorname{det}\left(J_{\partial \mathbf{t} / \partial \mathbf{x}}\right)^{-1}\left[\begin{array}{cc}
-5 x_{1}^{3} x_{2}^{2}+x_{2}^{5} & 5 x_{1}^{2} x_{2}^{3}-x_{1}^{5} \\
-3 x_{2}^{2} & 3 x_{1}^{2}
\end{array}\right]
$$

to obtain

$$
\nabla_{D}^{-1}(E)=\left(\frac{1}{28} x_{1}^{7}-\frac{1}{4} x_{1}^{4} x_{2}^{3}\right) \partial_{x_{1}}+\left(\frac{1}{28} x_{2}^{7}-\frac{1}{4} x_{1}^{3} x_{2}^{4}\right) \partial_{x_{2}} \in \operatorname{Der}_{S}^{W} .
$$

We finally obtain

$$
\begin{aligned}
\Theta_{1}:=\nabla_{\partial_{x_{1}}} \nabla_{D}^{-1}(E) & =\frac{\partial\left(\frac{1}{28} x_{1}^{7}-\frac{1}{4} x_{1}^{4} x_{2}^{3}\right)}{\partial x_{1}} \partial_{x_{1}}+\frac{\partial\left(\frac{1}{28} x_{2}^{7}-\frac{1}{4} x_{1}^{3} x_{2}^{4}\right)}{\partial x_{1}} \partial_{x_{2}} \\
& =\left(\frac{1}{4} x_{1}^{6}-x_{1}^{3} x_{2}^{3}\right) \partial_{x_{1}}-\frac{3}{4} x_{1}^{2} x_{2}^{4} \partial_{x_{2}} \\
\Theta_{2}:=\nabla_{\partial_{x_{2}}} \nabla_{D}^{-1}(E) & =\frac{\partial\left(\frac{1}{28} x_{1}^{7}-\frac{1}{4} x_{1}^{4} x_{2}^{3}\right)}{\partial x_{2}} \partial_{x_{1}}+\frac{\partial\left(\frac{1}{28} x_{2}^{7}-\frac{1}{4} x_{1}^{3} x_{2}^{4}\right)}{\partial x_{2}} \partial_{x_{2}} \\
& =-\frac{3}{4} x_{1}^{4} x_{2}^{2} \partial_{x_{1}}+\left(\frac{1}{4} x_{2}^{6}-x_{1}^{3} x_{2}^{3}\right) \partial_{x_{2}} .
\end{aligned}
$$

One can easily check that $\left\{\Theta_{1}, \Theta_{2}\right\}$ is indeed a homogeneous basis of $\mathfrak{D}(\mathscr{A}, \omega)$.

## 4. Proof of Theorem 1.2

In this section, we prove in Theorem 4.1 a strengthened version of Theorem 1.2 for the imprimitive groups $G(d e, e, \ell)$ with

$$
r:=d e \geq 2 \quad \text { and } \quad \ell \geq 2
$$

We fix these parameters throughout. This restriction means we exclude the symmetric groups $G(1,1, \ell)$ and the cyclic groups $G(d, 1,1)$ from our subsequent considerations. The first has been treated in [Ter02], the second is trivial.

Recall that the simple reflection arrangements in the considered cases are given by

$$
Q(\mathscr{A})=\left\{\begin{aligned}
\left(x_{1} \cdots x_{\ell}\right) \prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right) & \text { if } d>1, \\
\prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right) & \text { if } d=1,
\end{aligned}\right.
$$

see [OT92, Sec. 6.4]. Moreover,

$$
\begin{array}{ll}
e_{H}=d & \text { for } H=\operatorname{ker}\left(x_{i}\right) \text { with } 1 \leq i \leq \ell, \\
e_{H}=2 & \text { for } H=\operatorname{ker}\left(x_{i}-\zeta x_{j}\right) \text { with } 1 \leq i<j \leq \ell \text { and } \zeta^{r}=1 .
\end{array}
$$

The following theorem is our more general version of Theorem 1.2.
Theorem 4.1. Let $m, m_{1}, \ldots, m_{\ell}, \in \mathbb{N}$ such that $q:=\left\lfloor\left(m_{i}-1\right) / r\right\rfloor$ does not depend on $i$. Set $a:=(\ell-1) r, m^{\prime}:=\sum m_{i}$, and $c:=m a+q r+1$.
(i) The multi-arrangement $(\mathscr{A}, \mu)$ with defining polynomial

$$
Q(\mathscr{A}, \mu)=x_{1}^{m_{1}} \cdots x_{\ell}^{m_{\ell}} \prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m}
$$

is free with exponents

$$
\exp (\mathscr{A}, \mu)=\left\{m a+m_{1}, \ldots, m a+m_{\ell}\right\} .
$$

(ii) The multi-arrangement $(\mathscr{A}, \mu)$ with defining polynomial

$$
Q(\mathscr{A}, \mu)=x_{1}^{m_{1}} \cdots x_{\ell}^{m_{\ell}} \prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m+1}
$$

is free with exponents

$$
\begin{aligned}
\exp (\mathscr{A}, \mu)= & \left\{c+m^{\prime}-\ell(q r+1), \quad c+r, c+2 r, \ldots, c+(\ell-1) r\right\} \\
= & \left\{(m-q) a+m^{\prime}-\ell+1,\right. \\
& m a+(q+1) r+1, m a+(q+2) r+1, \ldots, m a+(q+\ell-1) r+1\}
\end{aligned}
$$

In (ii), we provide two alternative formulas for later reference. We prove the two parts of this theorem in Sections 4.1 and 4.2, respectively.

Armed with Theorem 4.1, we can deduce our second main result, Theorem 1.2. We treat the three cases $d=1, e=1$, and $d, e \geq 2$ separately, and observe that the first two are well-generated while the third is not.

Proof of Theorem 1.2 (i). For $d=1$, we have Coxeter number $h=(\ell-1) e$. Consider the defining polynomial

$$
Q(\mathscr{A}, m \omega)=\prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m} .
$$

This is the case $m_{1}=m_{2}=\ldots=m_{\ell}=0$ in Theorem 4.1(i). Thus, $(\mathscr{A}, m \omega)$ is free with

$$
\exp (\mathscr{A}, m \omega)=\{m(\ell-1) e, \ldots, m(\ell-1) e\}=\{m h, \ldots, m h\}
$$

as claimed.
For $e=1$, we have Coxeter number $h=\ell d$. Consider the defining polynomial

$$
Q(\mathscr{A}, m \omega)=x_{1}^{r m} \cdots x_{\ell}^{r m} \prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m}
$$

This is the case $m_{1}=m_{2}=\ldots=m_{\ell}=r m$ in Theorem 4.1(i). Thus, $(\mathscr{A}, m \omega)$ is free with

$$
\exp (\mathscr{A}, m \omega)=\{m \ell r, \ldots, m \ell r\}=\{m h, \ldots, m h\}
$$

as claimed.
For $d, e \geq 2$, we have Coxeter number $h=(\ell-1) r+d$. Consider the defining polynomial

$$
Q(\mathscr{A}, m \omega)=x_{1}^{d m} \cdots x_{\ell}^{d m} \prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m} .
$$

This is the case $m_{1}=m_{2}=\ldots=m_{\ell}=d m$ in Theorem 4.1(i). Thus, $(\mathscr{A}, m \omega)$ is free with

$$
\exp (\mathscr{A}, m \omega)=\{m((\ell-1) r+d), \ldots, m((\ell-1) r+d)\}=\{m h, \ldots, m h\}
$$

as claimed.

Proof of Theorem 1.2 (ii). For $d=1$, we have Coxeter number $h=(\ell-1) r$, and

$$
\left\{n_{1}\left(V^{*}\right), \ldots, n_{\ell}\left(V^{*}\right)\right\}=\{(\ell-1) r-\ell+1, \quad 1, r+1,2 r+1, \ldots,(\ell-2) r+1\}
$$

Consider the defining polynomial

$$
Q(\mathscr{A}, m \omega+1)=\prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m+1} .
$$

This is the case $m_{1}=m_{2}=\ldots=m_{\ell}=0$ in Theorem 4.1(ii). We have $a=(\ell-1) r, q=$ -1 , and $m^{\prime}=0$, and $(\mathscr{A}, m \omega+1)$ is free with

$$
\begin{aligned}
& \exp (\mathscr{A}, m \omega+1) \\
&=\{(m+1)(\ell-1) r-\ell+1, \\
&m(\ell-1) r+1, m(\ell-1) r+r+1, \ldots, m(\ell-1) r+(\ell-2) r+1\} \\
&=\{m h+(\ell-1) r-\ell+1, \quad m h+1, m h+r+1, \ldots, m h+(\ell-2) r+1\} \\
&=\left\{m h+n_{1}\left(V^{*}\right), \ldots, m h+n_{\ell}\left(V^{*}\right)\right\},
\end{aligned}
$$

as claimed.
For $e=1$, we have Coxeter number $h=\ell d$ and

$$
\left\{n_{1}\left(V^{*}\right), \ldots, n_{\ell}\left(V^{*}\right)\right\}=\{1, d+1,2 d+1, \ldots,(\ell-1) d+1\} .
$$

Consider the defining polynomial

$$
Q(\mathscr{A}, m \omega+1)=x_{1}^{d m+1} \cdots x_{\ell}^{d m+1} \prod_{1 \leq i<j \leq \ell}\left(x_{i}^{d}-x_{j}^{d}\right)^{2 m+1} .
$$

This is the case $r=d, m_{1}=m_{2}=\ldots=m_{\ell}=d m+1$ in Theorem 4.1(ii). We have $a=(\ell-1) d, q=m$, and $m^{\prime}=\ell d m+\ell$, and $(\mathscr{A}, m \omega+1)$ is free with

$$
\begin{aligned}
\exp (\mathscr{A}, m \omega+1)= & \{\ell d m+\ell-\ell+1, \\
& m(\ell-1) d+(m+1) d+1, \ldots, m(\ell-1) d+(m+\ell-1) d+1\} \\
= & \{m h+1, m h+d+1, \ldots, m h+(\ell-1) d+1\} \\
= & \left\{m h+n_{1}\left(V^{*}\right), \ldots, m h+n_{\ell}\left(V^{*}\right)\right\},
\end{aligned}
$$

as claimed.
For $d, e \geq 2$, we have Coxeter number $h=(\ell-1) d e+d$, and, as computed in [GG12, Sec. 3], we have $\operatorname{ord}(\Psi)=e$ with

$$
\begin{align*}
& \left\{n_{1}\left(\Psi^{s}\left(V^{*}\right)^{*}\right), \ldots, n_{\ell}\left(\Psi^{s}\left(V^{*}\right)^{*}\right)\right\}=  \tag{4.2}\\
& \quad\{d(s(\ell-1)+\ell-1, \quad d((\ell-1) e-s)-1, \ldots, d(2 e-s)-1, d(e-s)-1\}
\end{align*}
$$

for $0 \leq s<e$. We consider the defining polynomial

$$
Q(\mathscr{A}, \mu)=x_{1}^{d m+1} \cdots x_{\ell}^{d m+1} \prod_{1 \leq i<j \leq \ell}\left(x_{i}^{d e}-x_{j}^{d e}\right)^{2 m+1}
$$

This is the case $m_{1}=m_{2}=\ldots=m_{\ell}=d m+1$ in Theorem 4.1(ii). We have $a=$ $(\ell-1) d e, q=b$ with uniquely written $m=b e+s$ for $0 \leq s<e$, and $m^{\prime}=\ell d m+\ell$. Consequently, using (2.12) and (4.2), ( $\mathscr{A}, m \omega+1$ ) is free and

$$
\begin{aligned}
\exp (\mathscr{A}, m \omega+1)= & \{(m-b)(\ell-1) d e+\ell d m+1, \\
& (m(\ell-1)+b+1) d e+1, \ldots,(m(\ell-1)+b+(\ell-1)) d e+1\} \\
=\{ & (m+1)((\ell-1) d e+d)-d((e-s-1)(\ell-1)+\ell)+1, \\
& (m+1)((\ell-1) d e+d)-d((\ell-1) e-(e-1-s))+1, \ldots, \\
& (m+1)((\ell-1) d e+d)-d(e-(e-1-s))+1\} \\
= & \left\{(m+1) h-n_{1}\left(\Psi^{e-1-s}\left(V^{*}\right)^{*}\right), \ldots,(m+1) h-n_{\ell}\left(\Psi^{e-1-s}\left(V^{*}\right)^{*}\right)\right\} \\
= & \left\{(m+1) h-n_{1}\left(\Psi^{-m-1}\left(V^{*}\right)^{*}\right), \ldots,(m+1) h-n_{\ell}\left(\Psi^{-m-1}\left(V^{*}\right)^{*}\right)\right\} \\
= & \left\{m h+n_{1}\left(V^{*}\right), \ldots, m h+n_{\ell}\left(V^{*}\right)\right\},
\end{aligned}
$$

as claimed.
In the remainder of this section, we prove the two parts of Theorem 4.1 separately.
4.1. Proof of Theorem 4.1(i). We begin with the situation in rank 2 and set $S=\mathbb{C}[x, y]$ in this case.

Lemma 4.3. Let $r \geq 2, m \geq 1$ and $k \geq 0$. Define $(\mathscr{A}, \mu)$ by

$$
Q(\mathscr{A}, \mu)=x^{k r+1} y^{k r+1}\left(x^{r}-y^{r}\right)^{2 m} .
$$

Then $(\mathscr{A}, \mu)$ is free with

$$
\exp (\mathscr{A}, \mu)=\{(m+k) r+1,(m+k) r+1\} .
$$

Moreover, there are homogeneous polynomials $q_{1}, q_{2} \in \mathbb{Z}[x, y]$ of degrees $m$ and $m-1$, respectively, such that
(i) all coefficients of $q_{1}, q_{2}$ are non-zero, and
(ii) the homogeneous derivations

$$
\begin{aligned}
\theta_{1} & :=x^{k r+1} q_{1}\left(x^{r}, y^{r}\right) \partial_{x}+y^{k r+1} x^{r} q_{2}\left(x^{r}, y^{r}\right) \partial_{y} \\
\theta_{2} & :=x^{k r+1} y^{r} q_{2}\left(y^{r}, x^{r}\right) \partial_{x}+y^{k r+1} q_{1}\left(y^{r}, x^{r}\right) \partial_{y}
\end{aligned}
$$

form a basis of $\mathfrak{D}(\mathscr{A}, \mu)$.
Proof. We aim to define $q_{1}$ and $q_{2}$ such that $\theta_{1}(x-y) \in(x-y)^{2 m} S$. Let $q_{1}(x, y)=$ $\sum_{i=0}^{m} a_{i} x^{i} y^{m-i}$ and $q_{2}(x, y)=\sum_{i=0}^{m-1} b_{i} x^{i} y^{m-1-i}$ for some $a_{i}, b_{i} \in \mathbb{Q}$. Then

$$
P(x, y):=\theta_{1}(x-y)=\sum_{i=0}^{m} a_{i} x^{(i+k) r+1} y^{(m-i) r}-\sum_{i=0}^{m-1} b_{i} x^{(i+1) r} y^{(m-1-i+k) r+1} .
$$

Since we require $P(x, y) \in(x-y)^{2 m} S$, the coefficients $a_{0}, \ldots, a_{m}, b_{0}, \ldots, b_{m-1}$ form a solution of the following system of linear equations over $\mathbb{Q}$

$$
\left(\left(\frac{d}{d x}\right)^{j} P\right)(x, x)=0
$$

for $j=0, \ldots, 2 m-1$.

The entries of the corresponding matrix are just given by the exponents of $x$ in $q_{1}, q_{2}$. Dividing the $j$-th equation by $j$ !, the entries of the respective equations become

$$
\binom{(i+k) r+1}{j} \quad \text { and } \quad-\binom{(i+1) r}{j}
$$

for $a_{i}$ with $i=0, \ldots, m$, and, respectively, for $b_{i}$ with $i=0, \ldots, m-1$. We may avoid the minus sign by replacing $b_{i}$ by $-b_{i}$. The homogeneous system has $2 m$ equations and $2 m+1$ unknowns. Thus, we may choose a non-trivial solution with $a_{i}, b_{i} \in \mathbb{Z}$ for all $i$.
Now assume that one of the $a_{i}$ or one of the $b_{i}$ is zero, so that we may omit the corresponding summand in $q_{1}$ or $q_{2}$. This corresponds to deleting the coefficients of this monomial in the given system of equations. But then, the matrix for $j=0, \ldots, 2 m-1$ is a $(2 m \times 2 m)$-matrix, which is invertible thanks to the famous Gessel-Viennot lemma [GV85]. In this case, there is only the trivial solution. This contradicts the fact that we have already obtained a non-trivial solution in the previous paragraph. Hence, none of the $a_{i}$ or $b_{i}$ are zero.

Next, we check that $\theta_{1} \in \mathfrak{D}(\mathscr{A}, \mu)$. By construction, $\theta_{1}(x) \in x^{k r+1} S, \theta_{1}(y) \in y^{k r+1} S$ and $\theta_{1}(x-y) \in(x-y)^{2 m} S$. Then, for $\zeta$ an $r$-th root of unity, we have

$$
\begin{aligned}
\theta_{1}(x-\zeta y) & =x^{k r+1} q_{1}\left(x^{r}, y^{r}\right)-\zeta y^{k r+1} x^{r} q_{2}\left(x^{r}, y^{r}\right) \\
& =x^{k r+1} q_{1}\left(x^{r},(\zeta y)^{r}\right)-(\zeta y)^{k r+1} x^{r} q_{2}\left(x^{r},(\zeta y)^{r}\right) \\
& =P(x, \zeta y) \in(x-\zeta y)^{2 m} S .
\end{aligned}
$$

Hence $\theta_{1} \in \mathfrak{D}(\mathscr{A}, \mu)$. Likewise, we also get that $\theta_{2} \in \mathfrak{D}(\mathscr{A}, \mu)$. Observe that

$$
\operatorname{det} M\left(\theta_{1}, \theta_{2}\right)=x^{k r+1} y^{k r+1} q_{1}\left(x^{r}, y^{r}\right) q_{1}\left(y^{r}, x^{r}\right)-x^{(k+1) r+1} y^{(k+1) r+1} q_{2}\left(x^{r}, y^{r}\right) q_{2}\left(y^{r}, x^{r}\right)
$$

is non-zero of degree $|\mu|$. (The first part is only divisible by $x^{k r+1}$ and the second part is divisible by $x^{(k+1) r+1}$.) Thus $\theta_{1}$ and $\theta_{2}$ are independent over $S$. Since $\theta_{1}$ and $\theta_{2}$ are homogeneous and $\operatorname{pdeg} \theta_{1}+\operatorname{pdeg} \theta_{2}=|\mu|$, it follows from Theorem 2.1(iii) that $\left\{\theta_{1}, \theta_{2}\right\}$ is a basis of $\mathfrak{D}(\mathscr{A}, \mu))$.
Corollary 4.4. Let $r \geq 2, m \geq 1, k \geq 0$ and $m_{1}, m_{2} \geq 0$ such that $(k-1) r+1 \leq$ $m_{1}, m_{2} \leq k r+1$. Define $(\mathscr{A}, \mu)$ by

$$
Q(\mathscr{A}, \mu)=x^{m_{1}} y^{m_{2}}\left(x^{r}-y^{r}\right)^{2 m} .
$$

Then $(\mathscr{A}, \mu)$ is free with

$$
\exp (\mathscr{A}, \mu)=\left\{r m+m_{1}, r m+m_{2}\right\} .
$$

Proof. A basis $\left\{\tilde{\theta}_{1}, \tilde{\theta}_{2}\right\}$ of $\mathfrak{D}(\mathscr{A}, \mu)$ is given by

$$
\tilde{\theta}_{1}=\left\{\begin{array}{ll}
\theta_{1} / x & \text { if } k=0, \\
\theta_{1} / x^{r} & \text { if } k>0,
\end{array} \quad \text { and } \quad \tilde{\theta}_{2}= \begin{cases}\theta_{2} / y & \text { if } k=0, \\
\theta_{2} / y^{r} & \text { if } k>0,\end{cases}\right.
$$

where $\theta_{1}$ and $\theta_{2}$ are given as in Lemma 4.3.
We next use the rank 2 considerations to prove the general rank $\ell$ case.
Theorem 4.5. Let $\ell, r \geq 2, k \geq 0, m_{1}, \ldots, m_{\ell} \geq 0$ and $(k-1) r+1 \leq m_{1}, \ldots, m_{\ell} \leq k r+1$. Define $(\mathscr{A}, \mu)$ by

$$
Q(\mathscr{A}, \mu)=x_{1}^{m_{1}} \cdots x_{\ell}^{m_{\ell}} \prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m} .
$$

Then $\mathfrak{D}(\mathscr{A}, \mu)$ is free with

$$
\exp (\mathscr{A}, \mu)=\underset{19}{\left.c+m_{1}, \ldots, c+m_{\ell}\right\}}
$$

where $c=(\ell-1) m r$.
Proof. We argue by induction on $\ell$. Thanks to Corollary 4.4, the theorem holds for $\ell=2$. Now, suppose $\ell>2$. The proof in this case follows from a further induction on $\sum m_{i}$. Thanks to Theorem 1.1, the statement of the theorem holds for $m_{1}=\ldots=m_{\ell}=0$. Now let $\sum m_{i} \neq 0$. Without loss, we may assume that $m_{\ell}>0$ is maximal among the $m_{i}$. We aim to apply Theorem 2.2 with respect to the hyperplane $H_{\ell}=\operatorname{ker} x_{\ell}$. If $m_{1}=\cdots=m_{\ell}=(k-1) r+1$, then, in order to being able to apply the induction hypothesis, requiring the lower bounds on the $m_{i}$, we replace $k$ by $k-1$. Observe that this replacement is valid as, crucially, the exponents do not depend on $k$.

The defining polynomial of the deletion with respect to $H_{\ell}$ is given by

$$
Q\left(\mathscr{A}^{\prime}, \mu^{\prime}\right)=x_{1}^{m_{1}} \cdots x_{\ell-1}^{m_{\ell-1}} x_{\ell}^{m_{\ell}-1} \prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m} .
$$

Now, by induction on $\sum m_{i},\left(\mathscr{A}^{\prime}, \mu^{\prime}\right)$ is free with exponents

$$
\exp \left(\mathscr{A}^{\prime}, \mu^{\prime}\right)=\left\{c+m_{1}, \ldots, c+m_{\ell-1}, c+m_{\ell}-1\right\}
$$

The Euler multiplicity $\mu^{*}$ on $\mathscr{A}^{H_{\ell}}$ is given by

$$
Q\left(\mathscr{A}^{H_{\ell}}, \mu^{*}\right)=x_{1}^{m_{1}+r m} \cdots x_{\ell-1}^{m_{\ell-1}+r m} \prod_{1 \leq i<j \leq \ell-1}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m} .
$$

This can be seen as follows. For a hyperplane $H_{i j}=\operatorname{ker}\left(x_{i}-x_{j}\right)(i, j \neq \ell)$ the localization is of size $\left|\mathscr{A}_{H_{\ell} \cap H_{i j}}\right|=2$, hence the Euler multiplicity is $2 m$, by Lemma 2.3. For a hyperplane $H_{i}=\operatorname{ker} x_{i}(i \neq \ell)$ the localization is given by

$$
x_{i}^{m_{i}} x_{\ell}^{m_{\ell}}\left(x_{i}^{r}-x_{\ell}^{r}\right)^{2 m}
$$

with exponents $\left\{r m+m_{i}, r m+m_{\ell}\right\}$, by Corollary 4.4. By decreasing $m_{\ell}$, the second exponent changes, again according to Corollary 4.4. Hence the Euler multiplicity is $r m+m_{i}$.

Now, by induction on $\ell$, we know that $\left(\mathscr{A}^{H_{\ell}}, \mu^{*}\right)$ is free, and we compute the exponents as follows. The corresponding constant $c^{*}$ from the statement of the theorem is $c^{*}=$ $((\ell-1)-1) m r=c-m r$. Hence,

$$
\exp \left(\mathscr{A}^{H_{\ell}}, \mu^{*}\right)=\left\{c^{*}+m_{1}+m r, \ldots, c^{*}+m_{\ell-1}+m r\right\}=\left\{c+m_{1}, \ldots, c+m_{\ell-1}\right\} .
$$

The theorem now follows by Theorem 2.2.
Note that Theorem 4.1(i) follows from Theorem 4.5.
4.2. Proof of Theorem 4.1(ii). The derivations are constructed in a similar way as in the previous case. Hence we construct a polynomial whose coefficients are the solution of a system of linear equations which depend on several indeterminates. The key observation in the previous case was the regularity of a matrix whose entries consist of certain binomial coefficients. It turns out that in the present case the entries of the matrix consist of differences of certain binomial coefficients. The application of the following technical lemma in the present situation was communicated to us by Christian Krattenthaler.

Lemma 4.6 ([Kra99, Lem. 7]). Let $X_{1}, X_{2}, \ldots, X_{m}, A_{2}, A_{3}, \ldots, A_{m}, C$ be indeterminates, and let $p_{0}, p_{1}, \ldots, p_{m-1}$ be polynomials in a single variable such that $\operatorname{deg} p_{j} \leq 2 j$ and $p_{j}(X)=p_{j}(C-X)$ for $j=0,1, \ldots, m-1$. Then,

$$
\operatorname{det}_{1 \leq i, j \leq m}\left(\prod_{k=j+1}^{m}\left(\left(X_{i}-A_{k}\right)\left(X_{i}-A_{k}-C\right)\right) \cdot p_{j-1}\left(X_{i}\right)\right)
$$

$$
=\prod_{1 \leq i<j \leq m}\left(X_{j}-X_{i}\right)\left(C-X_{i}-X_{j}\right) \prod_{i=1}^{m} p_{i-1}\left(-A_{i}\right)
$$

Comparing the coefficient of $A_{m}^{2 m-2} A_{m-1}^{2 m-4} \cdots A_{1}^{0}$ in the identity in the previous lemma, we obtain

$$
\begin{equation*}
\operatorname{det}_{1 \leq i, j \leq m}\left(p_{j-1}\left(X_{i}\right)\right)=\prod_{1 \leq i<j \leq m}\left(X_{i}-X_{j}\right)\left(C-X_{i}-X_{j}\right) \prod_{i=1}^{m} q_{i-1} \tag{4.7}
\end{equation*}
$$

where $q_{j}$ is the leading coefficient of $p_{j}(X)$.
Utilizing (4.7), we obain the following consequence.
Corollary 4.8. Let $A, B, m \in \mathbb{N}$ such that $A-B \not \equiv 0 \bmod r$, and $\operatorname{set} C=\frac{B-A}{r}$, $X_{i}=i-1$, and

$$
p_{j}(X)=\frac{1}{A-B+2 r X}\left(\binom{A+r X}{2 j+1}-\binom{B-r X}{2 j+1}\right) \in \mathbb{Q}[X]
$$

Then the left-hand side of (4.7) specializes to

$$
\operatorname{det}_{0 \leq i, j \leq m-1}\left(\binom{A+r i}{2 j+1}-\binom{B-r i}{2 j+1}\right)
$$

which is not identically zero.
We use this corollary repeatedly in the subsequent lemma.
Lemma 4.9. Let $m \geq 1$ and $k \geq 0$. Define $(\mathscr{A}, \mu)$ by

$$
Q(\mathscr{A}, \mu)=x^{k r+1} y^{k r+1}\left(x^{r}-y^{r}\right)^{2 m+1} .
$$

Then $(\mathscr{A}, \mu)$ is free with

$$
\exp (\mathscr{A}, \mu)=\{(m+k) r+1,(m+k+1) r+1\}
$$

Moreover, there are polynomials $q_{1}, q_{2} \in \mathbb{Z}[x, y]$ of degree $m$ such that
(i) the coefficients of $x^{m}$ and $y^{m}$ in $q_{1}, q_{2}$ are non-zero and
(ii) the homogeneous derivations

$$
\begin{aligned}
\theta_{1} & :=x^{k r+1} q_{1}\left(x^{r}, y^{r}\right) \partial_{x}+y^{k r+1} q_{1}\left(y^{r}, x^{r}\right) \partial_{y} \\
\theta_{2} & :=x^{k r+1} y^{r} q_{2}\left(x^{r}, y^{r}\right) \partial_{x}+y^{k r+1} x^{r} q_{2}\left(y^{r}, x^{r}\right) \partial_{y}
\end{aligned}
$$

form a basis of $\mathfrak{D}(\mathscr{A}, \mu)$.
Proof. We aim to define $q_{1}$ such that $\theta_{1}(x-y) \in(x-y)^{2 m+1} S$. Let $q_{1}=\sum_{i=0}^{m} a_{i} x^{i} y^{m-i}$ with $a_{i} \in \mathbb{Q}$. We require that

$$
P(x, y):=\theta_{1}(x-y)=\sum_{i=0}^{m} a_{i}\left(x^{(i+k) r+1} y^{(m-i) r}-x^{(m-i) r} y^{(i+k) r+1}\right) \in(x-y)^{2 m+1} S
$$

Hence, the coefficients $a_{0}, \ldots, a_{m}$ form a solution of the following system of linear equations over $\mathbb{Q}$

$$
\begin{equation*}
\frac{1}{j!}\left(\left(\frac{d}{d x}\right)^{j} P\right)(x, x)=0 \tag{4.10}
\end{equation*}
$$

for $j=0, \ldots, 2 m$. Since $P(x, y)=-P(y, x)$, the identity (4.10) holds for a given even $j$, provided it holds for all $j^{\prime}$ with $0 \leq j^{\prime}<j$. (In particular, it holds for $j=0$.)

Because we have $m+1$ variables and $m$ equations, the system has a non-trivial solution. We may choose one such non-trivial solution with coefficients in $\mathbb{Z}$.

Suppose $a_{m}=0$. Then we may remove the last column of the matrix in (4.10). The determinant of this matrix equals

$$
\operatorname{det}_{0 \leq i, j \leq m-1}\left(\binom{(i+k) r+1}{2 j+1}-\binom{(m-i) r}{2 j+1}\right)
$$

which is not identically zero, thanks to Corollary 4.8 for the parameters $A=k r+1$ and $B=m r$. Hence, (4.10) only admits the trivial solution, contradicting the above choice of a non-trivial solution.

Suppose $a_{0}=0$. Then we may remove the first column of the matrix in (4.10). Its determinant equals, after substituting $i$ by $i+1$, the determinant

$$
\operatorname{det}_{0 \leq i, j \leq m-1}\left(\binom{(i+k+1) r+1}{2 j+1}-\binom{(m-i-1) r}{2 j+1}\right)
$$

which is not identically zero, again thanks to Corollary 4.8 for the parameters $A=$ $(k+1) r+1$ and $B=(m-1) r$. Hence, we obtain an analogous contradiction as in the previous case.

Next, we check that $\theta_{1} \in \mathfrak{D}(\mathscr{A}, \mu)$. By construction, $\theta_{1}(x) \in x^{k r+1} S, \theta_{1}(y) \in y^{k r+1} S$ and $\theta_{1}(x-y) \in(x-y)^{2 m+1} S$. Then, for $\zeta$ an $r$-th root of unity, we have

$$
\begin{aligned}
\theta_{1}(x-\zeta y) & =x^{k r+1} q_{1}\left(x^{r}, y^{r}\right)-\zeta y^{k r+1} q_{1}\left(y^{r}, x^{r}\right) \\
& =x^{k r+1} q_{1}\left(x^{r},(\zeta y)^{r}\right)-(\zeta y)^{k r+1} q_{1}\left((\zeta y)^{r}, x^{r}\right) \\
& =P(x, \zeta y) \in(x-\zeta y)^{2 m+1} S .
\end{aligned}
$$

We aim to define $q_{2}$ such that $\theta_{2}(x-y) \in(x-y)^{2 m+1} S$. Let $q_{2}=\sum_{i=0}^{m} b_{i} x^{i} y^{m-i}$ with $a_{i} \in \mathbb{Q}$. We require that

$$
\tilde{P}(x, y):=\theta_{2}(x-y)=\sum_{i=0}^{m} b_{i}\left(x^{(i+k) r+1} y^{(m-i+1) r}-x^{(m-i+1) r} y^{(k+i) r+1}\right) \in(x-y)^{2 m+1} S .
$$

Hence the coefficients of $q_{2}$ are the solutions of the system of equations given by

$$
\begin{equation*}
\frac{1}{j!}\left(\left(\frac{d}{d x}\right)^{j} \tilde{P}\right)(x, x)=0 \tag{4.11}
\end{equation*}
$$

for $j=0, \ldots, 2 m$. As above, since $\tilde{P}(x, y)=-\tilde{P}(y, x)$, we again observe that the equation holds for a given even $j$, provided it holds for all $j^{\prime}$ with $0 \leq j^{\prime}<j$.

Because we have $m+1$ variables and $m$ equations, the system has a non-trivial solution. We may choose one such non-trivial solution with coefficients in $\mathbb{Z}$.

Suppose $b_{m}=0$. Then we may remove the last column of the matrix in (4.11). The determinant of this matrix equals

$$
\operatorname{det}_{0 \leq i, j \leq m-1}\left(\binom{(i+k) r+1}{2 j+1}-\binom{(m-i+1) r}{2 j+1}\right)
$$

which is not identically zero, thanks to Corollary 4.8 for the parameters $A=k r+1$ and $B=(m+1) r$. Hence, (4.11) only admits the trivial solution, contradicting the above choice of a non-trivial solution.

Suppose $b_{0}=0$. Then we may remove the first column of the matrix in (4.11). Its determinant equals, after substituting $i$ by $i+1$, the determinant

$$
\operatorname{det}_{0 \leq i, j \leq m-1}\left(\binom{(i+k+1) r+1}{2 j+1}-\binom{(m-i) r}{2 j+1}\right)
$$

which is not identically zero, again thanks to Corollary 4.8 for the parameters $A=$ $(k+1) r+1$ and $B=m r$. Hence, we obtain an analogous contradiction as in the previous case.

Finally, we check that $\theta_{2} \in \mathfrak{D}(\mathscr{A}, \mu)$. By construction, $\theta_{2}(x) \in x^{k r+1} S, \theta_{2}(y) \in y^{k r+1} S$ and $\theta_{2}(x-y) \in(x-y)^{2 m+1} S$. Then, for $\zeta$ an $r$-th root of unity, we have

$$
\begin{aligned}
\theta_{2}(x-\zeta y) & =x^{k r+1} y^{r} q_{2}\left(x^{r}, y^{r}\right)-\zeta y^{k r+1} x^{r} q_{2}\left(y^{r}, x^{r}\right) \\
& =x^{k r+1}(\zeta y)^{r} q_{2}\left(x^{r},(\zeta y)^{r}\right)-(\zeta y)^{k r+1} x^{r} q_{2}\left((\zeta y)^{r}, x^{r}\right) \\
& =\tilde{P}(x, \zeta y) \in(x-\zeta y)^{2 m+1} S .
\end{aligned}
$$

Hence $\theta_{1}, \theta_{2} \in \mathfrak{D}(\mathscr{A}, \mu)$. Observe that

$$
\operatorname{det} M\left(\theta_{1}, \theta_{2}\right)=x^{(k+1) r+1} y^{k r+1} q_{1}\left(x^{r}, y^{r}\right) q_{2}\left(y^{r}, x^{r}\right)-y^{(k+1) r+1} x^{k r+1} q_{1}\left(y^{r}, x^{r}\right) q_{2}\left(x^{r}, y^{r}\right)
$$

This determinant has degree $|\mu|$. Since $q_{1}$ and $q_{2}$ are not divisible by $x$ and $y$, respectively, the determinant is non-zero. Thus $\theta_{1}$ and $\theta_{2}$ are independent over $S$. Since $\theta_{1}$ and $\theta_{2}$ are homogeneous and pdeg $\theta_{1}+\operatorname{pdeg} \theta_{2}=|\mu|$, it follows from Theorem 2.1(iii) that $\left\{\theta_{1}, \theta_{2}\right\}$ is a basis of $\mathfrak{D}(\mathscr{A}, \mu))$.

Corollary 4.12. Let $m \geq 1$ and $k \geq 0$. Let $0 \leq \tilde{m}_{1}, \tilde{m}_{2} \leq r$ and set $m_{i}:=(k-1) r+1+\tilde{m}_{i}$ for $i=1,2$ such that $m_{1}, m_{2} \geq 0$. Define $(\mathscr{A}, \mu)$ by

$$
Q(\mathscr{A}, \mu)=x^{m_{1}} y^{m_{2}}\left(x^{r}-y^{r}\right)^{2 m+1} .
$$

Let $c:=(k-1+m) r+1$. Then $(\mathscr{A}, \mu)$ is free with

$$
\exp (\mathscr{A}, \mu)=\left\{c+\tilde{m}_{1}+\tilde{m}_{2}, c+r\right\} .
$$

Proof. A basis $\left\{\tilde{\theta}_{1}, \tilde{\theta}_{2}\right\}$ of $\mathfrak{D}(\mathscr{A}, \mu)$ is given by $\tilde{\theta}_{1}=\theta_{1}$ and

$$
\tilde{\theta}_{2}= \begin{cases}\theta_{2} / x y & \text { if } k=0 \\ \theta_{2} / x^{r} y^{r} & \text { if } k>0\end{cases}
$$

where $\theta_{1}$ and $\theta_{2}$ are given as in Lemma 4.9.
Theorem 4.13. Let $k, m \geq 0$ and $0 \leq \tilde{m}_{1}, \ldots, \tilde{m}_{\ell} \leq r$. Set $m_{i}:=(k-1) r+1+\tilde{m}_{i}$ for $i \in\{1, \ldots, \ell\}$ such that $m_{i} \geq 0$, and set $c:=((\ell-1) m+k-1) r+1$.

Define $(\mathscr{A}, \mu)$ by

$$
Q(\mathscr{A}, \mu)=x_{1}^{m_{1}} \cdots x_{\ell}^{m_{\ell}} \prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m+1}
$$

Then $(\mathscr{A}, \mu)$ is free with

$$
\exp (\mathscr{A}, \mu)=\left\{c+\sum_{i=1}^{\ell} \tilde{m}_{i}, c+r, c+2 r, \ldots, c+(\ell-1) r\right\}
$$

Proof. We argue by induction on $\ell$. By Corollary 4.12, the theorem holds for $\ell=2$.
Suppose $\ell>2$. The proof in this case follows from a further induction on $\sum m_{i}$. Thanks to Theorem 1.1, the theorem holds for $m_{1}=\cdots=m_{\ell}=0$. Now let $\sum m_{i} \neq 0$. Without loss, we may assume that $m_{\ell}>0$ is maximal among the $m_{i}$. We aim to apply Theorem 2.2 with respect to the hyperplane $H_{\ell}=\operatorname{ker} x_{\ell}$. If $m_{1}=\cdots=m_{\ell}=(k-1) r+1$, then, in order to being able to apply the induction hypothesis, requiring the lower bounds on the $m_{i}$, we replace $k$ by $k-1$, and, simultaneously, replace $\tilde{m}_{i}=0$ by $\tilde{m}_{i}=r$ for all $i$. Observe that this replacement is valid as it does not change the arrangement and, crucially, the exponents also coincide in both cases.

The defining polynomial of the deletion with respect to $H_{\ell}$ is given by

$$
Q\left(\mathscr{A}^{\prime}, \mu^{\prime}\right)=x_{1}^{m_{1}} \cdots x_{\ell-1}^{m_{\ell-1}} x_{\ell}^{m_{\ell}-1} \prod_{1 \leq i<j \leq \ell}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m+1}
$$

Now, by induction on $\sum m_{i}$, the deletion $\left(\mathscr{A}^{\prime}, \mu^{\prime}\right)$ is free with exponents

$$
\exp \left(\mathscr{A}^{\prime}, \mu^{\prime}\right)=\left\{c-1+\sum_{i=1}^{\ell} \tilde{m}_{i}, c+r, c+2 r, \ldots, c+(\ell-1) r\right\} .
$$

The Euler multiplicity $\mu^{*}$ on $\mathscr{A}^{H_{\ell}}$ is given by

$$
Q\left(\mathscr{A}^{H_{\ell}}, \mu^{*}\right)=x_{1}^{(k+m) r+1} \cdots x_{\ell-1}^{(k+m) r+1} \prod_{1 \leq i<j \leq \ell-1}\left(x_{i}^{r}-x_{j}^{r}\right)^{2 m+1}
$$

This can be seen as follows.
For a hyperplane $H_{i j}=\operatorname{ker}\left(x_{i}-x_{j}\right)(i, j \neq \ell)$ the localization is of size $\left|\mathscr{A}_{H_{\ell} \cap H_{i j}}\right|=2$, hence the Euler multiplicity is $2 m+1$ by Lemma 2.3. For a hyperplane $H_{i}=\operatorname{ker} x_{i}(i \neq \ell)$ the localization is given by

$$
x_{i}^{m_{i}} x_{\ell}^{m_{\ell}}\left(x_{i}^{r}-x_{\ell}^{r}\right)^{2 m+1}
$$

with exponents $\left(\tilde{c}+\tilde{m}_{i}+\tilde{m}_{\ell},(k+m) r+1\right)$, by Corollary 4.12 , and by decreasing $m_{\ell}$, the first exponent changes, again according to Corollary 4.12. Hence the Euler multiplicity is $(k+m) r+1$.

Now, by induction on $\ell$, we know that $\left(\mathscr{A}^{H_{\ell}}, \mu^{*}\right)$ is free, and we compute the exponents as follows. The corresponding constant $c^{*}$ from the statement of the theorem is $c^{*}=$ $((l-2) m+k+m) r+1=((l-1) m+k-1) r+r+1=c+r$. Hence,

$$
\exp \left(\mathscr{A}^{H_{\ell}}, \mu^{*}\right)=\left\{c^{*}, c^{*}+r, \ldots, c^{*}+(\ell-2) r\right\}=\{c+r, c+2 r, \ldots, c+(\ell-1) r\} .
$$

The theorem now follows by Theorem 2.2.
Note that Theorem 4.1(ii) follows from Theorem 4.13.

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